

# MULTI-GPU PROGRAMMING FOR CUDA C++

# INTRODUCTION

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Main Objectives

**Concurrency Strategies** 

Workshop Structure

Increase performance for Single-Node CUDA C/C++ applications by exploiting, and then combining, 2 concurrency strategies offered to CUDA programmers.

Increase performance for Single-Node CUDA C/C++ applications by exploiting, and then combining, 2 concurrency strategies offered to CUDA programmers:

1) Overlapping memory transfers to and from the GPU with computations on the GPU

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- 1) Overlapping memory transfers to and from the GPU with computations on the GPU
- 2) Performing computations concurrently on more than one GPU

# CONCURRENCY STRATEGIES

GPU programming is usually a 3-step process

1. Transfer data to GPU device(s)

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сору

2. Perform computation on GPU device(s)

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3. Transfer data back to the host





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сору



 $\rightarrow$ 



...total application time will be less

 $\rightarrow$ 



≻

≻

сору

сору	
	compute
	compute
	compute

≻



...total application time will also be less

 $\rightarrow$ 



Combining the 2 strategies...

...overlapping compute on multiple devices

 $\rightarrow$ 

compute

compute

compute

...and copy with each device's compute



 $\rightarrow$ 

...total application time will be even less

 $\rightarrow$ 



Increase performance for Single-Node CUDA C/C++ applications by exploiting, and then combining, 2 concurrency strategies offered to CUDA programmers:

- 1) Overlapping memory transfers to and from the GPU with computations on the GPU
- 2) Performing computations concurrently on more than one GPU

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Next Steps



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