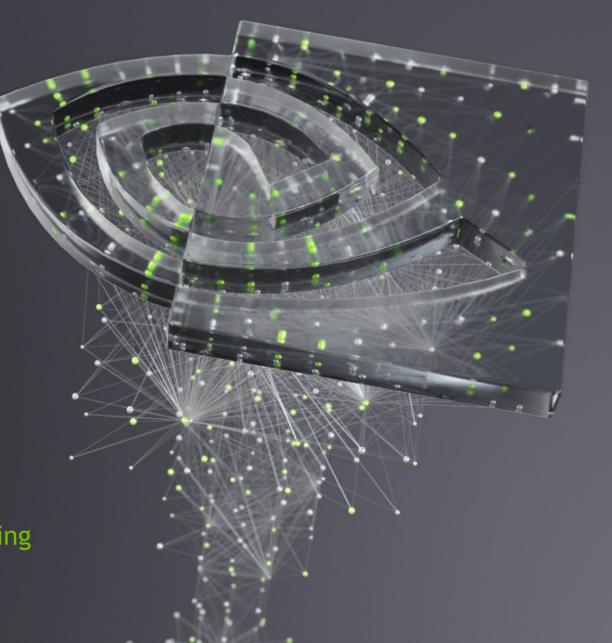
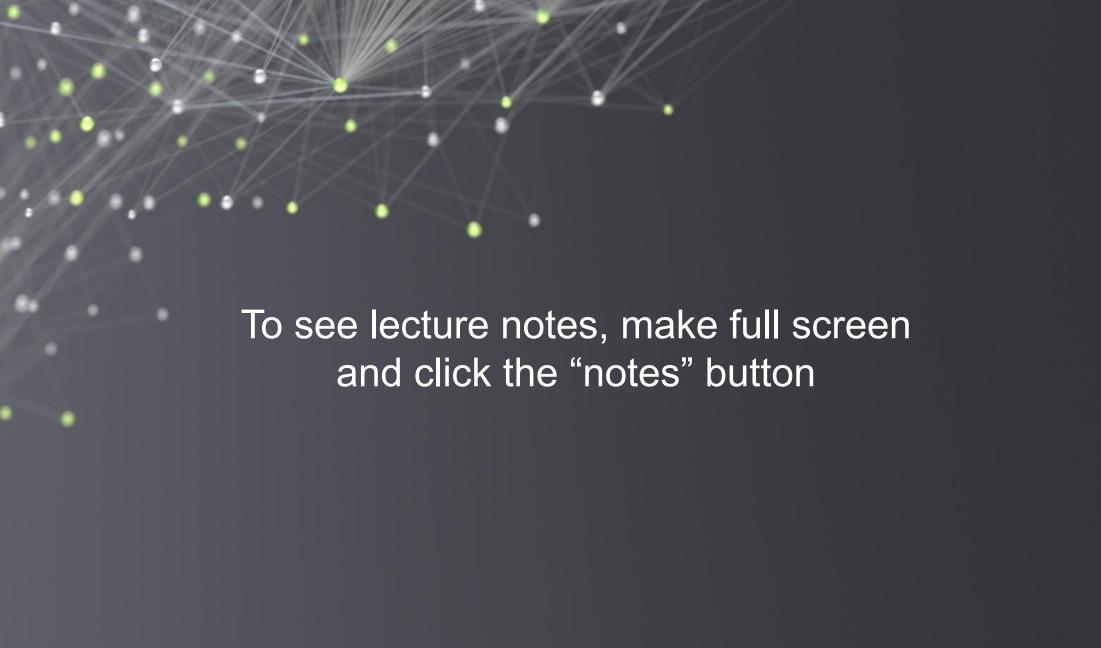


FUNDAMENTALS OF DEEP LEARNING

Part 1: An Introduction to Deep Learning







THE GOALS OF THIS COURSE

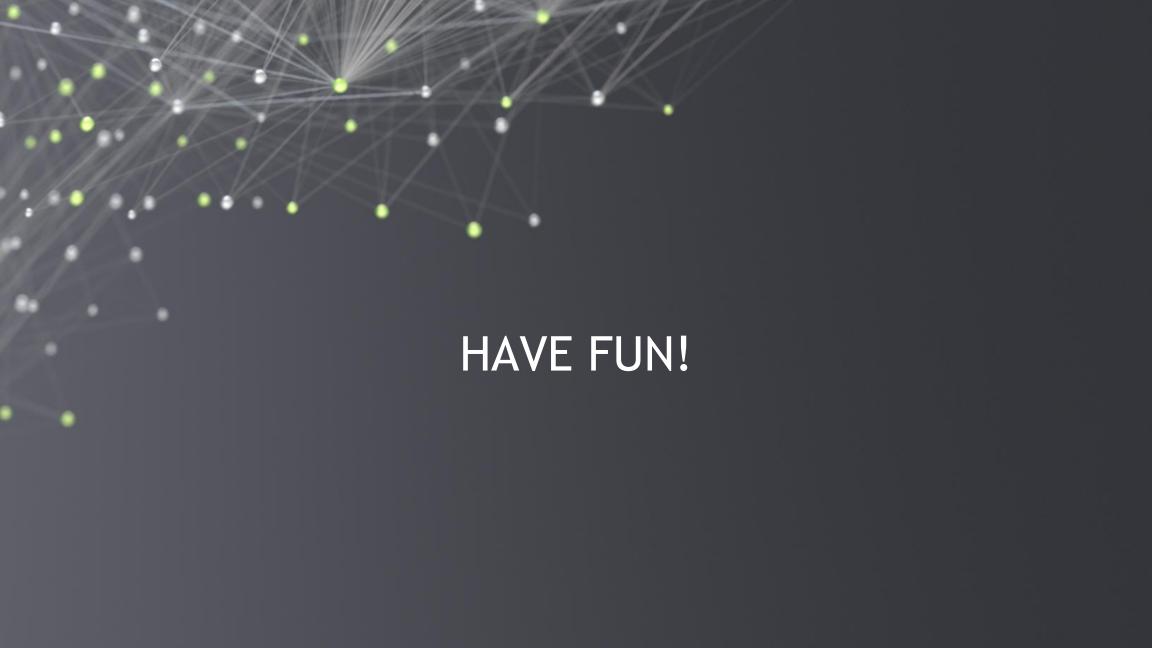
- Get you up and on your feet quickly
- Build a foundation to tackle a deep learning project right away
- We won't cover the whole field, but we'll get a great head start
- Foundation from which to read articles, follow tutorials, take further classes

AGENDA

Part I:An Introduction to Deep Learning Part 2: How a Neural Network Trains Part 3: Convolutional Neural Networks Part 4: Data Augmentation and Deployment Part 5: Pre-trained Models Part 6: Advanced Architectures

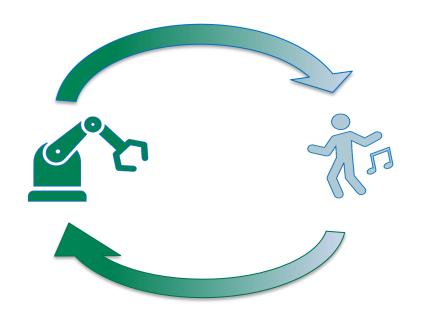
AGENDA – PART I

- History of Al
- The Deep Learning Revolution
- What is Deep Learning
- How Deep Learning is Transforming the World
- Overview of the Course
- First Exercise



HUMAN VS MACHINE LEARNING

Relaxed Alertness



Human	Machine
Rest and Digest	Training
Fight-or-flight	Prediction





BEGINNING OF ARTIFICIAL INTELLIGENCE



COMPUTERS ARE MADE IN PART TO COMPLETE HUMAN TASKS



EARLY ON, GENERALIZED INTELLIGENCE LOOKED POSSIBLE



TURNED OUT TO BE HARDER
THAN EXPECTED

EARLY NEURAL NETWORKS



Inspired by biology

Created in the 1950's

Outclassed by Von Neumann Architecture

EXPERT SYSTEMS



Highly complex



Programmed by hundreds of engineers



Rigorous programming of many rules



EXPERT SYSTEMS - LIMITATIONS

What are these three images?







HOW DO CHILDREN LEARN?



- Expose them to lots of data
- Give them the "correct answer"
- They will pick up the important patterns on their own



DATA

- Networks need a lot of information to learn from
- The digital era and the internet has supplied that data

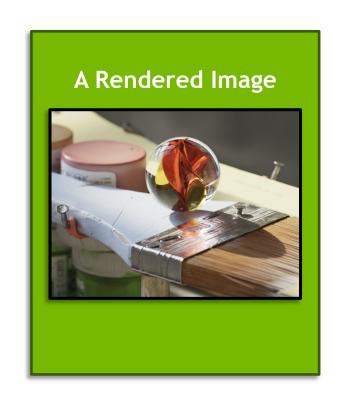


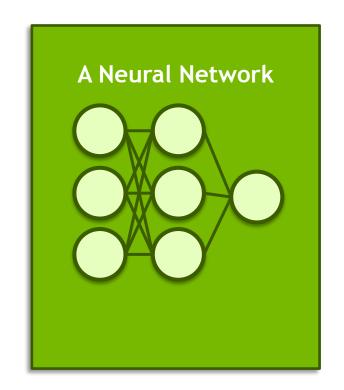
COMPUTING POWER

Need a way for our artificial "brain" to observe lots of data within a practical amount of time.



THE IMPORTANCE OF THE GPU







DEEP LEARNING FLIPS TRADITIONAL PROGRAMMING ON ITS HEAD

TRADITIONAL PROGRAMMING

Building a Classifier



Define a set of rules for classification



Program those rules into the computer



Feed it examples, and the program uses the rules to classify

MACHINE LEARNING

Building a Classifier

1

Show model the examples with the answer of how to classify



Model takes guesses, we tell it if it's right or not



Model learns to correctly categorize as it's training. The system learns the rules on its own



THIS IS A FUNDAMENTAL SHIFT

WHEN TO CHOOSE DEEP LEARNING

Classic Programming

If rules are clear and straightforward, often better to just program it

Deep Learning

If rules are nuanced, complex, difficult to discern, use deep learning

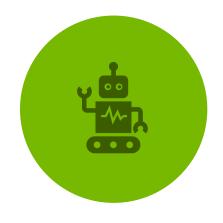
DEEP LEARNING COMPARED TO OTHER AI

Depth and complexity of networks Up to billions of parameters (and growing) Many layers in a model Important for learning complex rules





COMPUTER VISION



ROBOTICS AND MANUFACTURING



OBJECT DETECTION



SELF DRIVING CARS

NATURAL LANGUAGE PROCESSING







VOICE RECOGNITION



VIRTUAL ASSISTANTS

RECOMMENDER SYSTEMS



CONTENT CURATION



TARGETED ADVERTISING



SHOPPING RECOMMENDATIONS

REINFORCEMENT LEARNING



ALPHAGO BEATS WORLD CHAMPION IN GO



AI BOTS BEAT PROFESSIONAL VIDEOGAMERS



STOCK TRADING ROBOTS



HANDS ON EXERCISES

- Get comfortable with the process of deep learning
- Exposure to different models and datatypes
- Get a jump-start to tackle your own projects



STRUCTURE OF THE COURSE

"Hello World" of Deep Learning

Train a more complicated model

New architectures and techniques to improve performance

Pre-trained models

Transfer learning

PLATFORM OF THE COURSE



GPU powered cloud server



JupyterLab platform

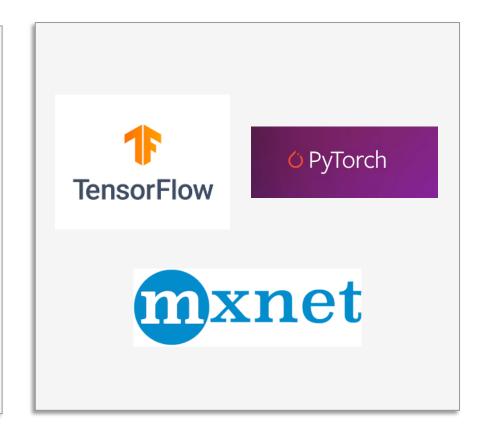


Jupyter notebooks for interactive coding



SOFTWARE OF THE COURSE

- Major deep learning platforms:
 - TensorFlow + Keras (Google)
 - Pytorch (Facebook)
 - MXNet (Apache)
- We'll be using TensorFlow and Keras
- Good idea to gain exposure to others moving forward





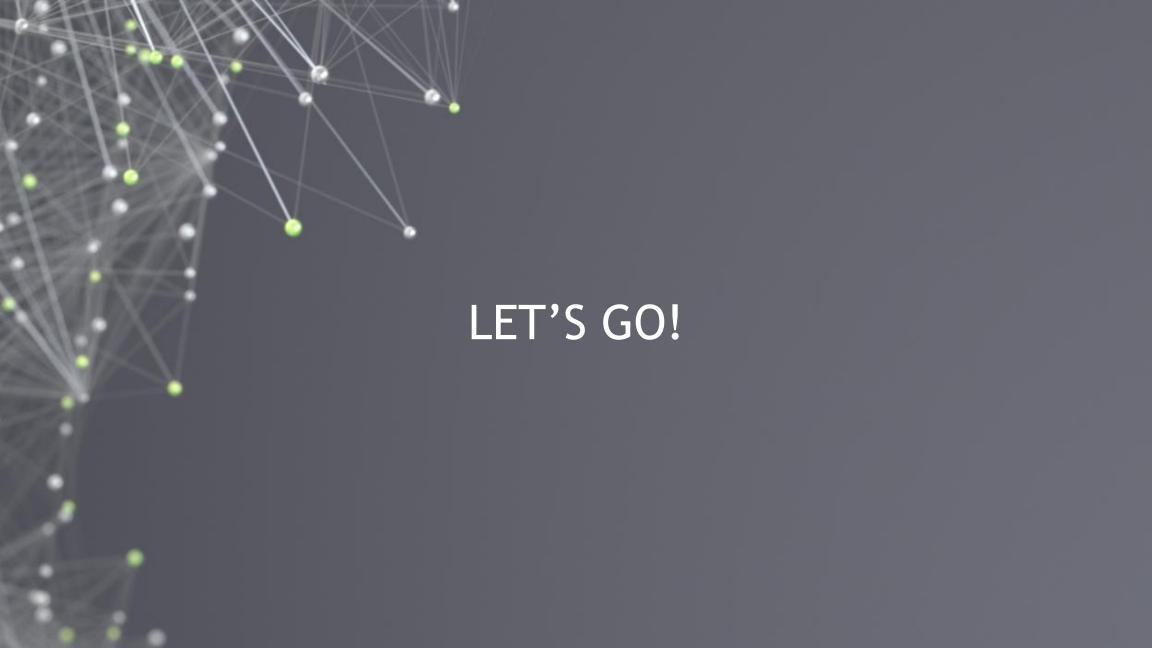
HELLO NEURAL NETWORKS

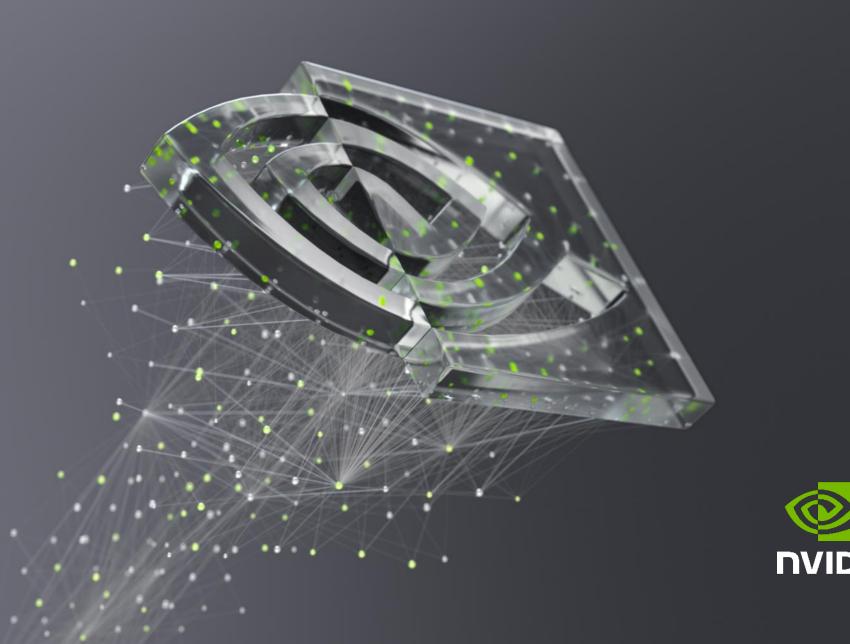
Train a network to correctly classify handwritten digits

 Historically important and difficult task for computers

Try learning like a Neural Network

 Get exposed to the example, and try to figure out the rules to how it works



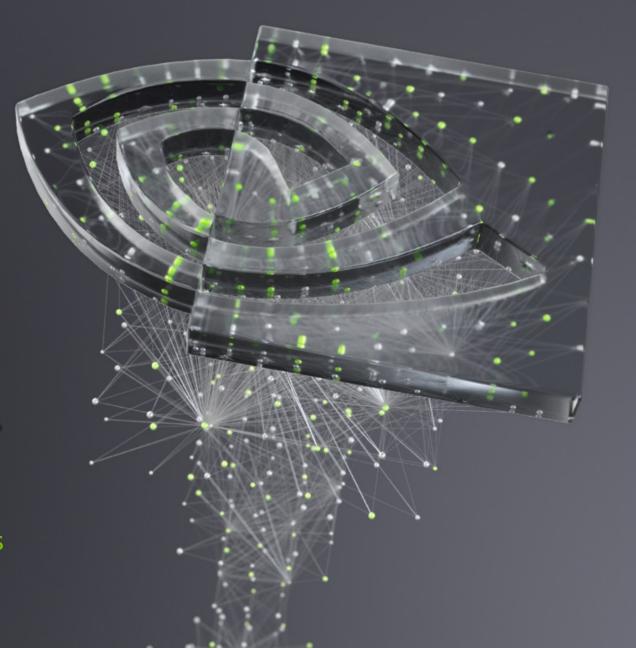






FUNDAMENTALS OF DEEP LEARNING

Part 2: How a Neural Network Trains



Part 1: An Introduction to Deep Learning Part 2: How a Neural Network Trains Part 3: Convolutional Neural Networks Part 4: Data Augmentation and Deployment Part 5: Pre-trained Models Part 6: Advanced Architectures

RECAP OF THE EXERCISE

What just happened?

Loaded and visualized our data

Edited our data (reshaped, normalized, to categorical)

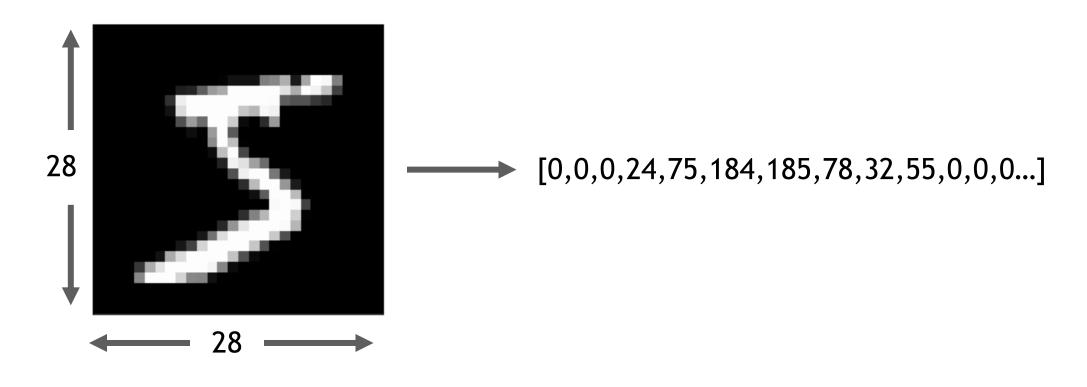
Created our model

Compiled our model

Trained the model on our data

DATA PREPARATION

Input as an array

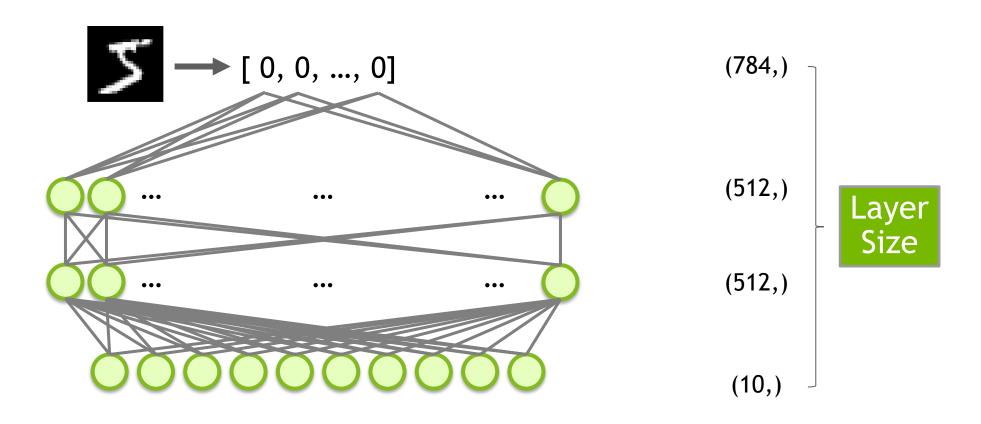


DATA PREPARATION

Targets as categories

0		[1,0,0,0,0,0,0,0,0,0]
1		[0,1,0,0,0,0,0,0,0]
2		[0,0,1,0,0,0,0,0,0,0]
3		[0,0,0,1,0,0,0,0,0,0]
	•	

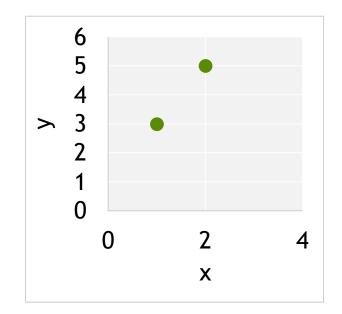
AN UNTRAINED MODEL

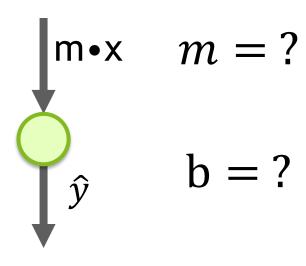




$$y = mx + b$$

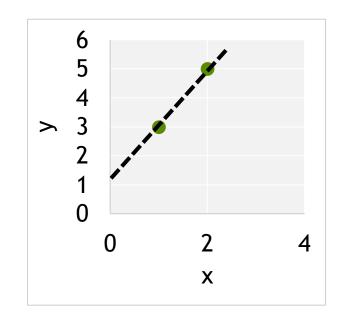
X	у
1	3
2	5

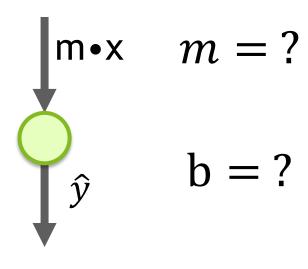




$$y = mx + b$$

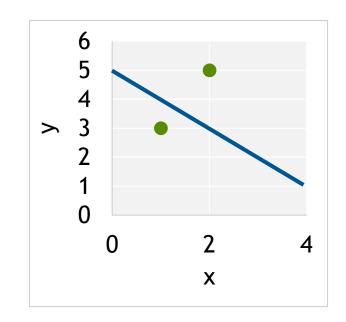
x	у
1	3
2	5

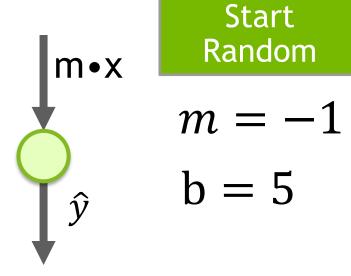




$$y = mx + b$$

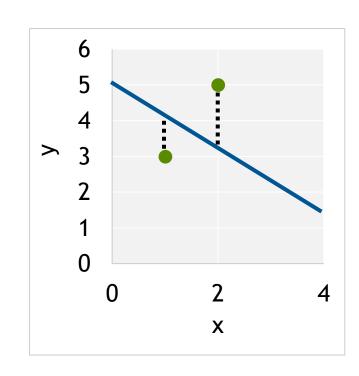
x	у	ŷ
1	3	4
2	5	3





$$y = mx + b$$

X	у	ŷ	err ²
1	3	4	1
2	5	3	4
MSE =			2.5
	1.6		

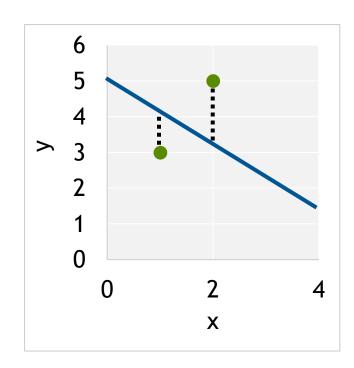


$$MSE = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2$$

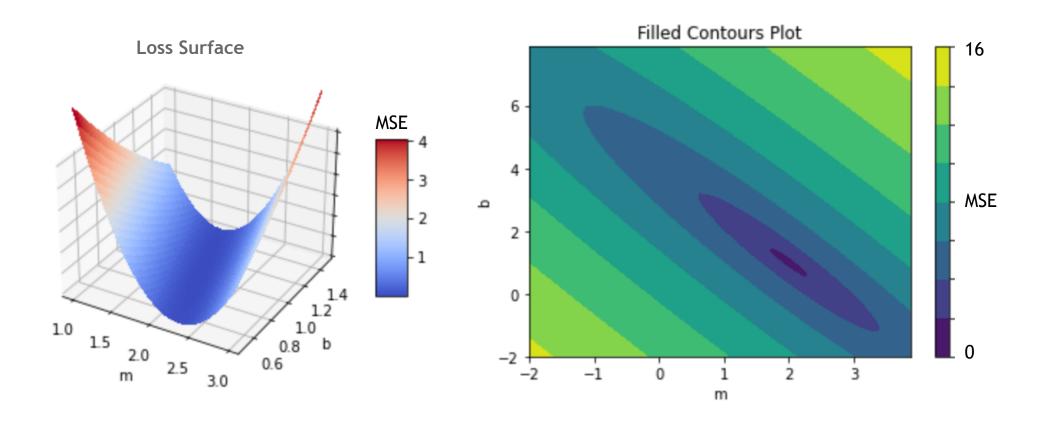
$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2}$$

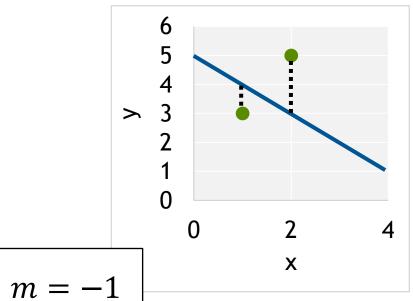
$$y = mx + b$$

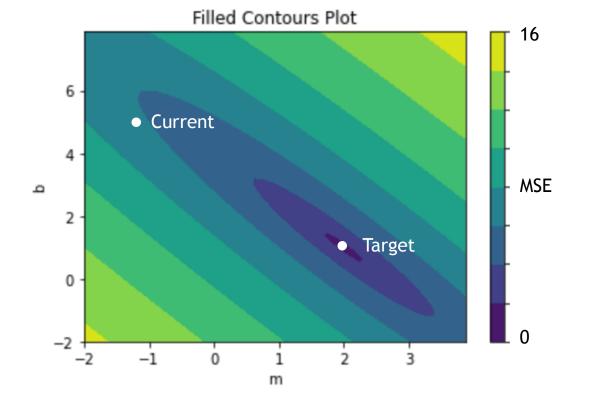
X	у	ŷ	err ²
1	3	4	1
2	5	3	4
MSE =			2.5
RMSE =			1.6

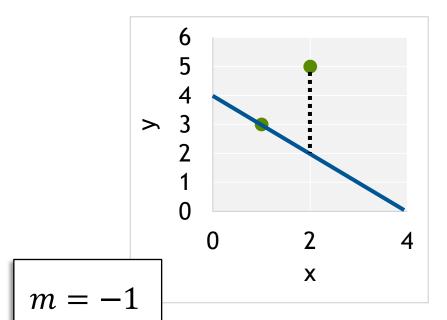


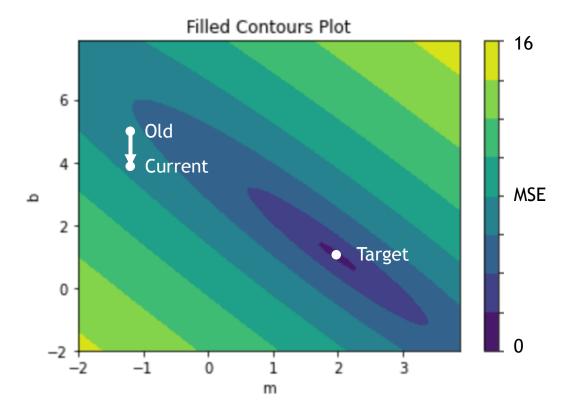
```
data = [(1, 3), (2, 5)]
    m = -1
    b = 5
    def get_rmse(data, m, b):
         """Calculates Mean Square Error"""
        n = len(data)
        squared error = 0
        for x, y in data:
11
            # Find predicted y
12
            y hat = m*x+b
13
            # Square difference between
14
            # prediction and true value
15
            squared_error += (
16
                y - y hat)**2
        # Get average squared difference
        mse = squared_error / n
        # Square root for original units
        return mse ** .5
20
```

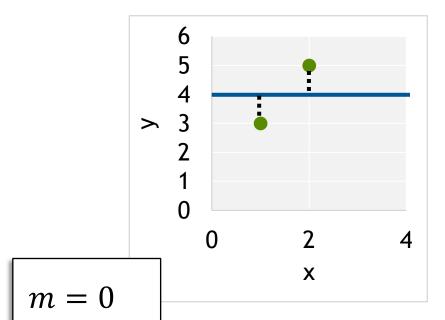


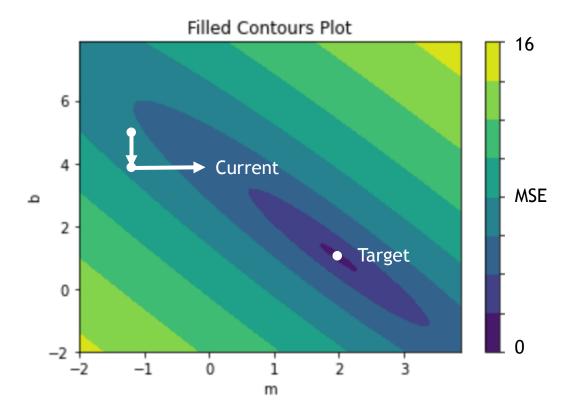


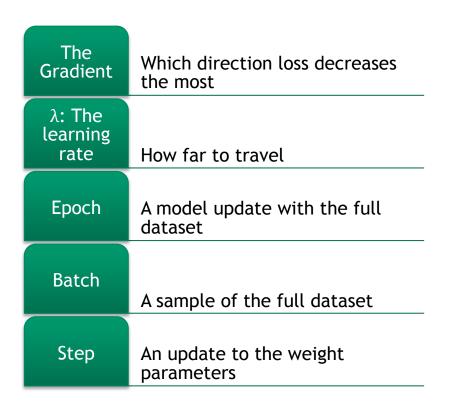


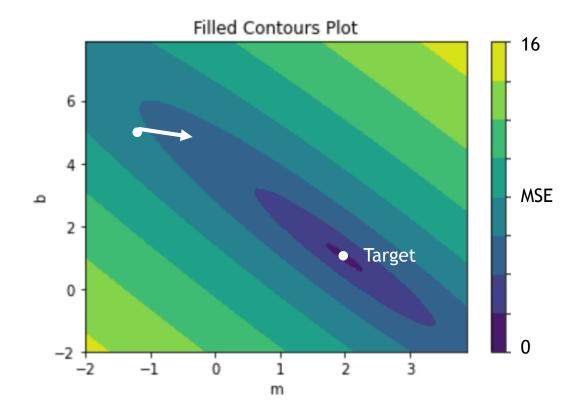


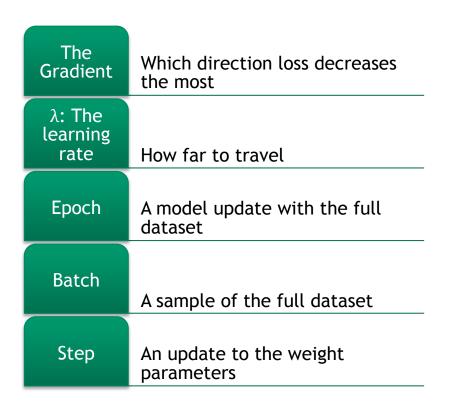


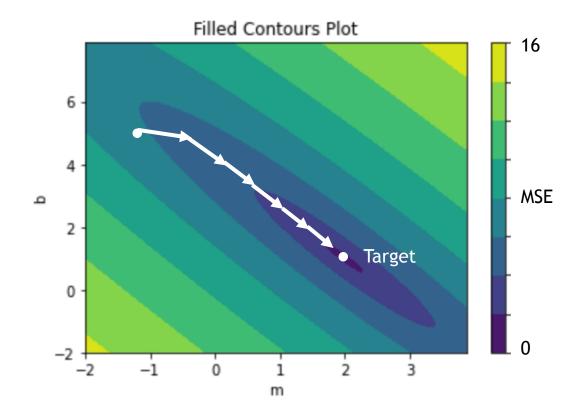




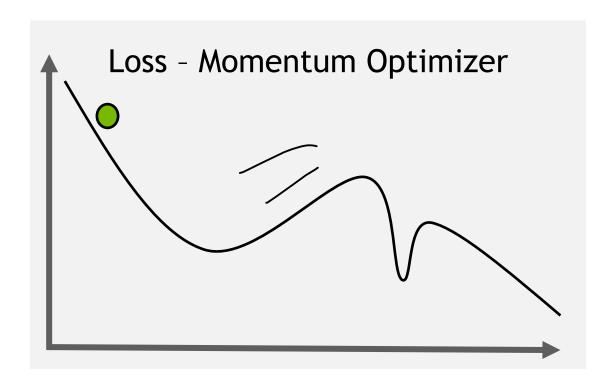








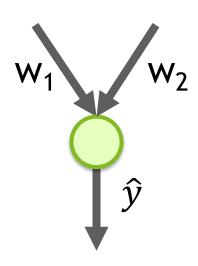
OPTIMIZERS



- Adam
- Adagrad
- RMSprop
- SGD

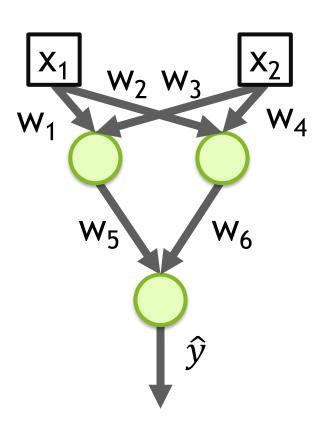


BUILDING A NETWORK



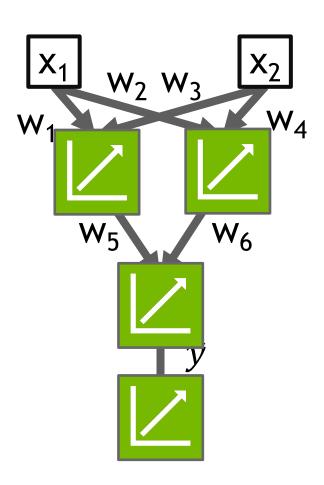
• Scales to more inputs

BUILDING A NETWORK



- Scales to more inputs
- Can chain neurons

BUILDING A NETWORK



- Scales to more inputs
- Can chain neurons
- If all regressions are linear, then output will also be a linear regression





ACTIVATION FUNCTIONS

Linear

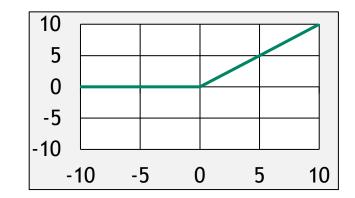
$$\hat{y} = wx + b$$

- # Multiply each input # with a weight (w) and # add intercept (b) y hat = wx+b
- 10 -5 -10 -5 -10 5 10

ReLU

$$\hat{y} = \begin{cases} wx + b & \text{if } wx + b > 0 \\ 0 & \text{otherwise} \end{cases}$$

```
# Only return result
# if total is positive
linear = wx+b
y_hat = linear * (linear > 0)
```

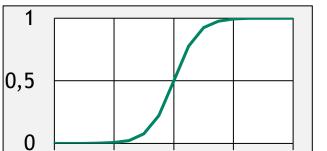


Sigmoid

$$\hat{y} = \frac{1}{1 + e^{-(wx+b)}}$$

```
# Start with line
2 linear = wx + b
   # Warp to - inf to 0
   inf_to_zero = np.exp(-1 * linear)
```

y hat = 1 / (1 + inf to zero)



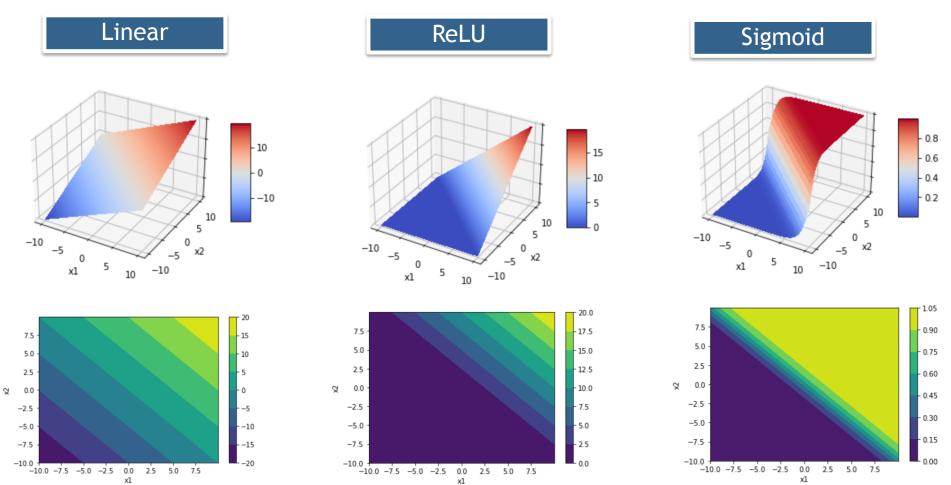
0

-5

-10

10

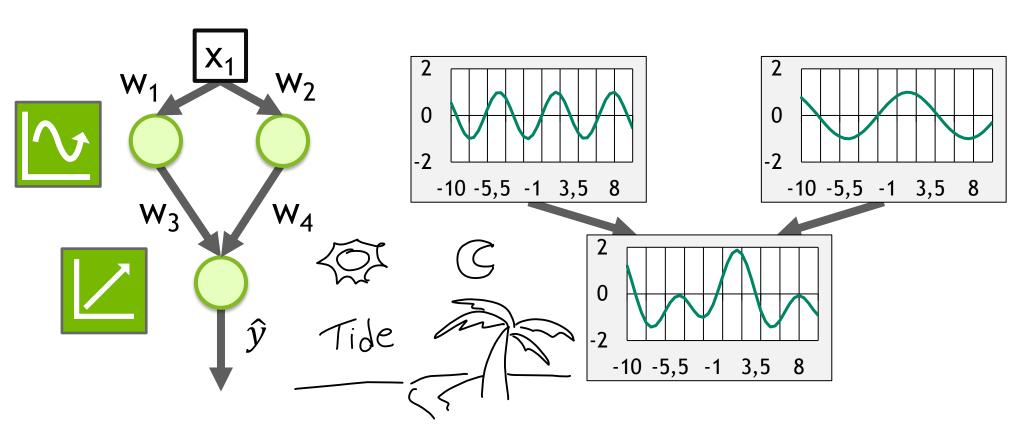
ACTIVATION FUNCTIONS







ACTIVATION FUNCTIONS

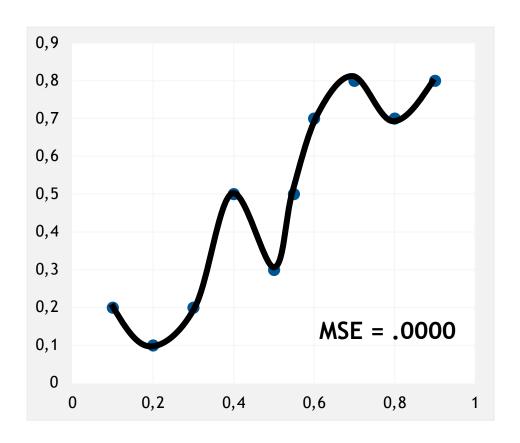


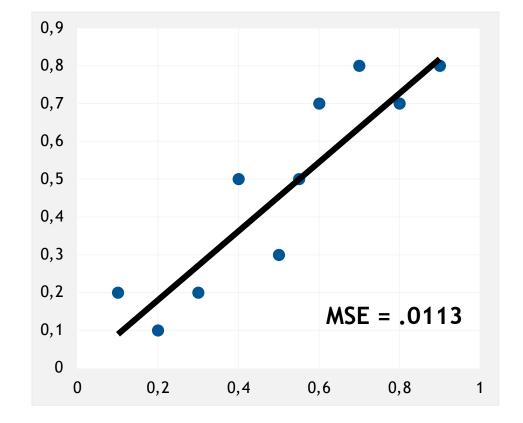


OVERFITTINGWhy not have a super large neural network?

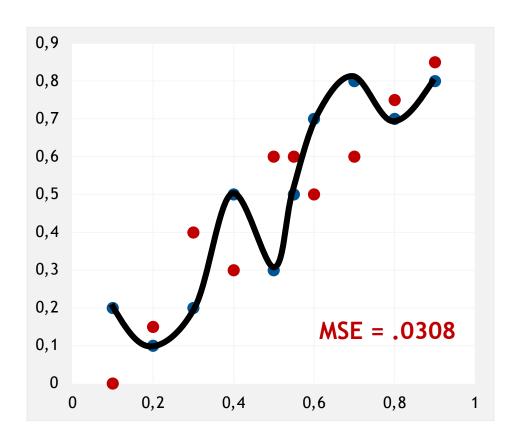


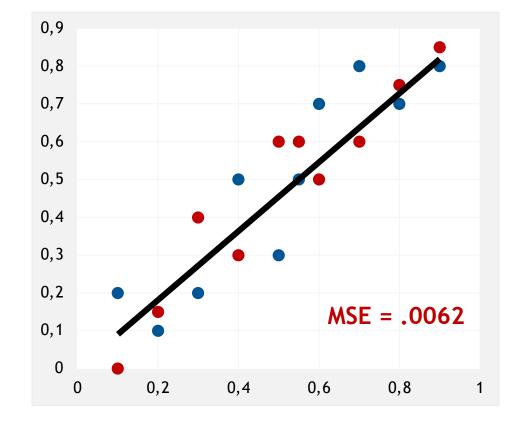
OVERFITTINGWhich Trendline is Better?





OVERFITTINGWhich Trendline is Better?





TRAINING VS VALIDATION DATA

Avoid memorization

Training data

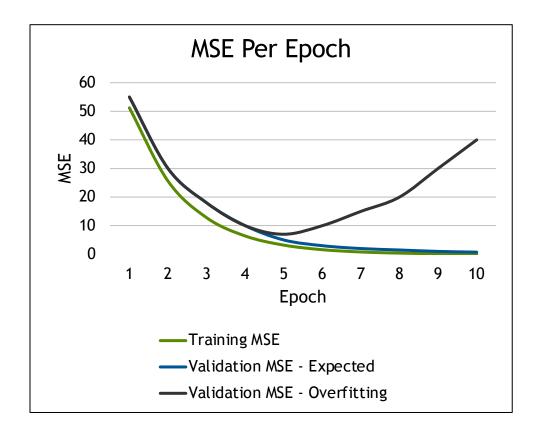
Core dataset for the model to learn on

Validation data

 New data for model to see if it truly understands (can generalize)

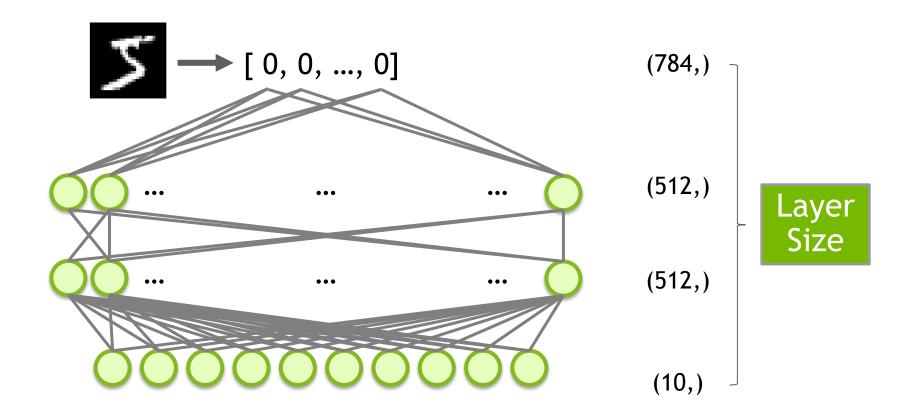
Overfitting

- When model performs well on the training data, but not the validation data (evidence of memorization)
- Ideally the accuracy and loss should be similar between both datasets

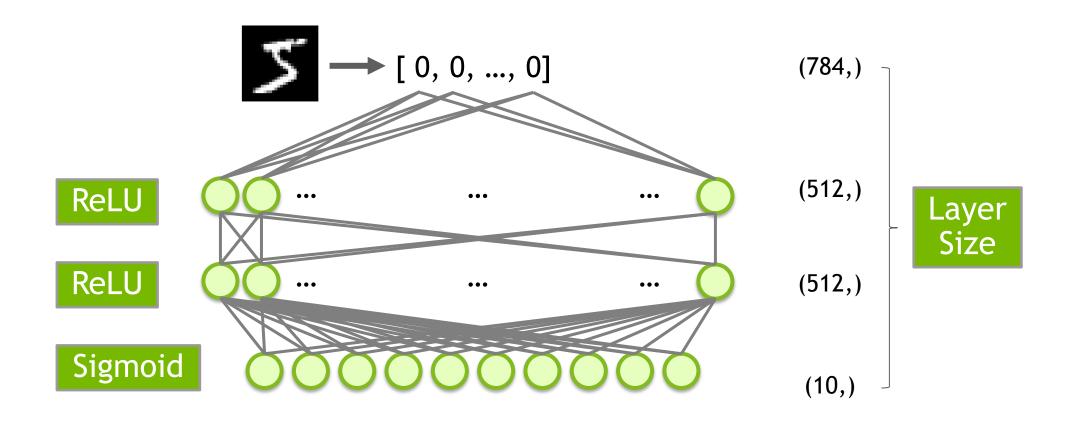




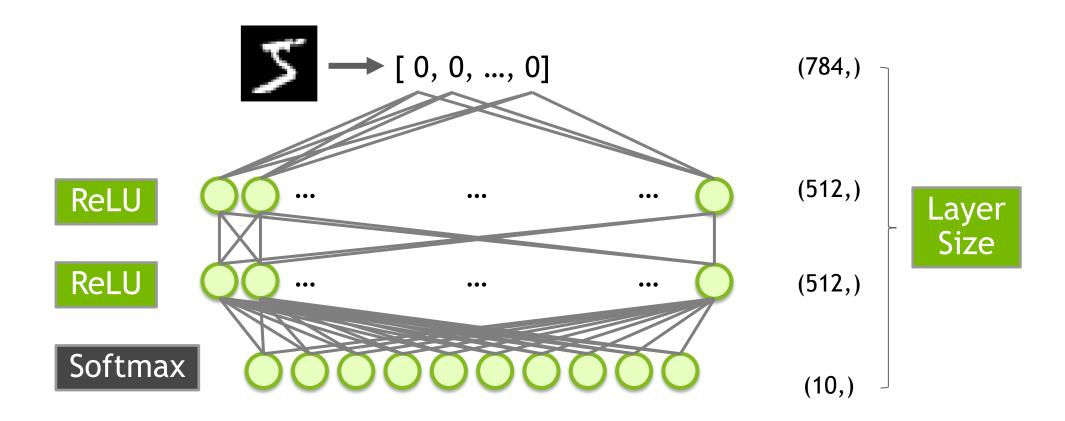
AN MNIST MODEL



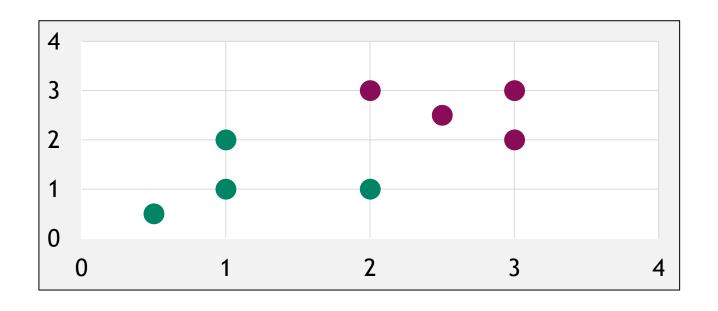
AN MNIST MODEL



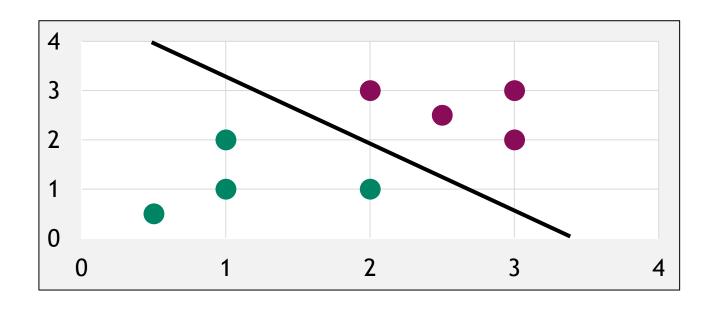
AN MNIST MODEL



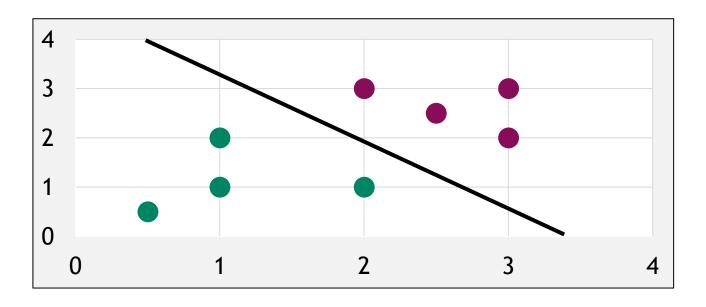
RMSE FOR PROBABILITIES?

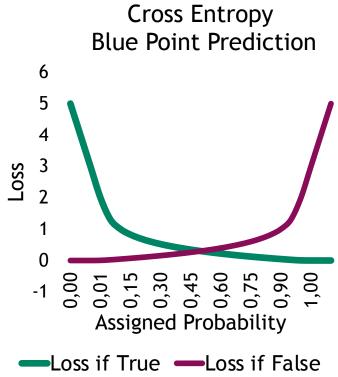


RMSE FOR PROBABILITIES?

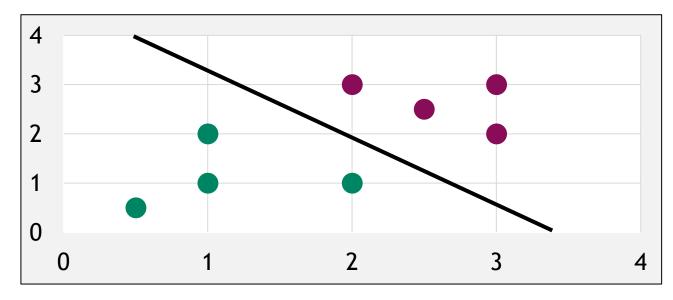


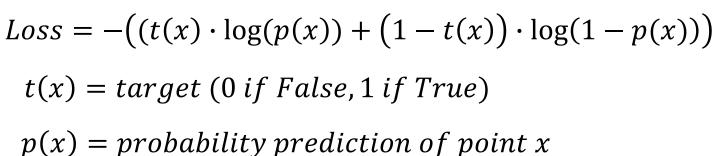
CROSS ENTROPY

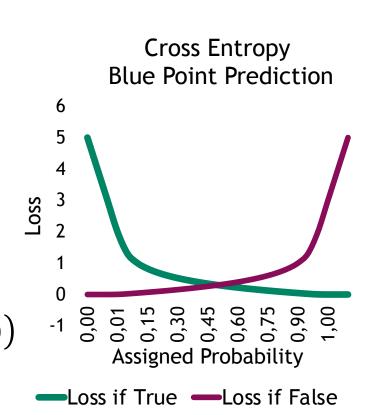




CROSS ENTROPY

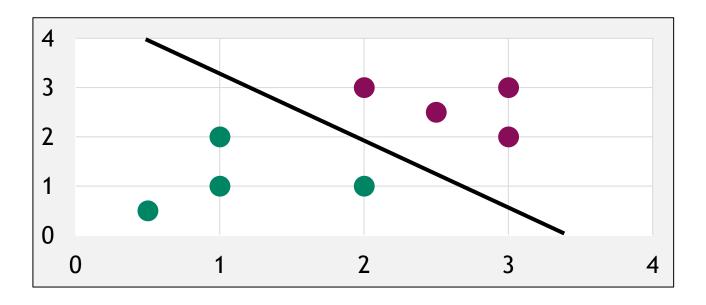




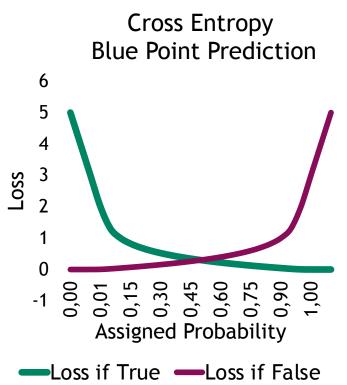




CROSS ENTROPY



```
1 def cross_entropy(y_hat, y_actual):
2    """Infinite error for misplaced confidence."""
3    loss = log(y_hat) if y_actual else log(1-y_hat)
4    return -1*loss
```

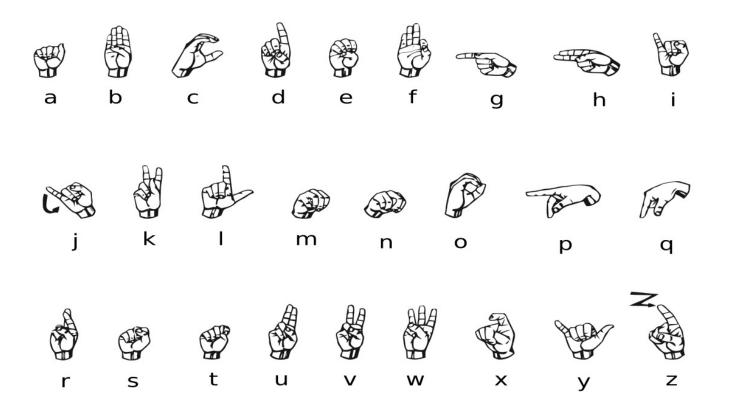






THE NEXT EXERCISE

The American Sign Language Alphabet

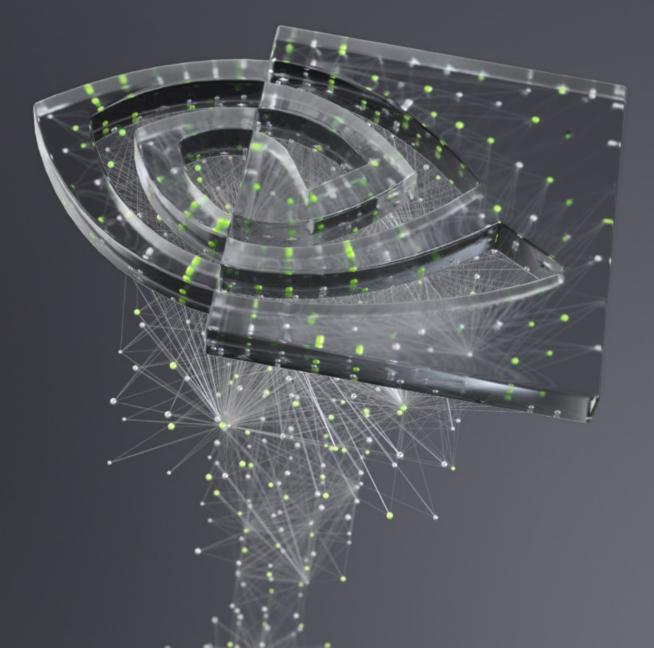






APPENDIX: GRADIENT DESCENT

HELPING THE COMPUTER CHEAT CALCULUS

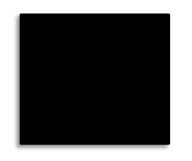


$$MSE = \frac{1}{n} \sum_{i=1}^{n} (y - \hat{y})^2 = \frac{1}{n} \sum_{i=1}^{n} (y - (mx + b))^2$$

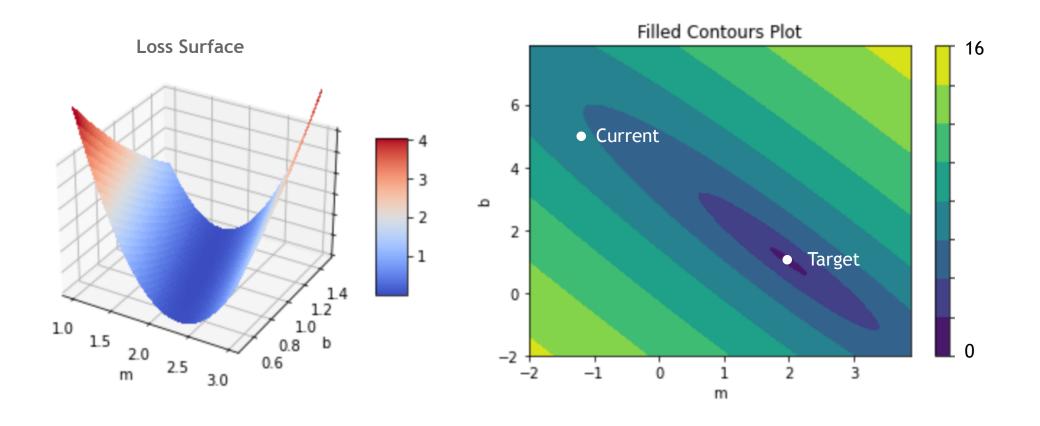
$$MSE = \frac{1}{2}((3 - (m(1) + b))^2 + (5 - (m(2) + b))^2)$$

$$\frac{\partial MSE}{\partial m} = 5m + 3b - 13 \qquad \qquad \frac{\partial MSE}{\partial b} = 3m + 2b - 8$$

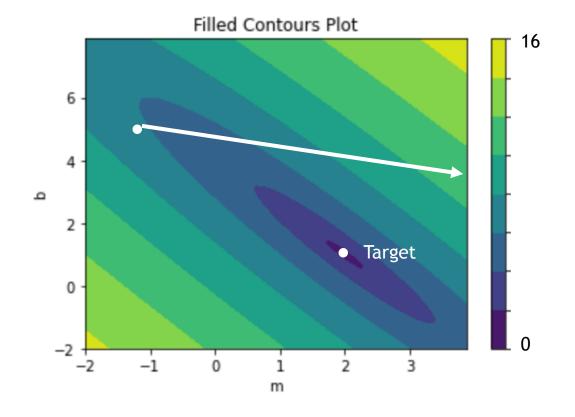
$$\frac{\partial MSE}{\partial m} = -3 \qquad \qquad \frac{\partial MSE}{\partial b} = -1$$







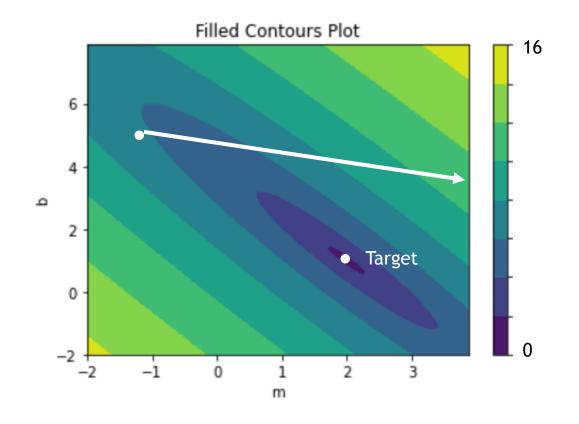
$$\frac{\partial MSE}{\partial m} = -7 \qquad \frac{\partial MSE}{\partial b} = -3$$



$$\frac{\partial MSE}{\partial m} = -7 \qquad \frac{\partial MSE}{\partial b} = -3$$

$$\mathbf{m} := \mathbf{m} - \lambda \frac{\partial MSE}{\partial m}$$

$$b \coloneqq b - \lambda \frac{\partial MSE}{\partial b}$$

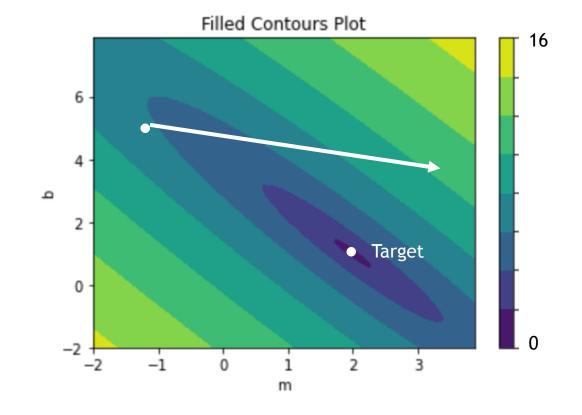


 $\lambda = .6$

$$\frac{\partial MSE}{\partial m} = -7 \qquad \frac{\partial MSE}{\partial b} = -3$$

$$\mathbf{m} := \mathbf{m} - \lambda \, \frac{\partial MSE}{\partial m}$$

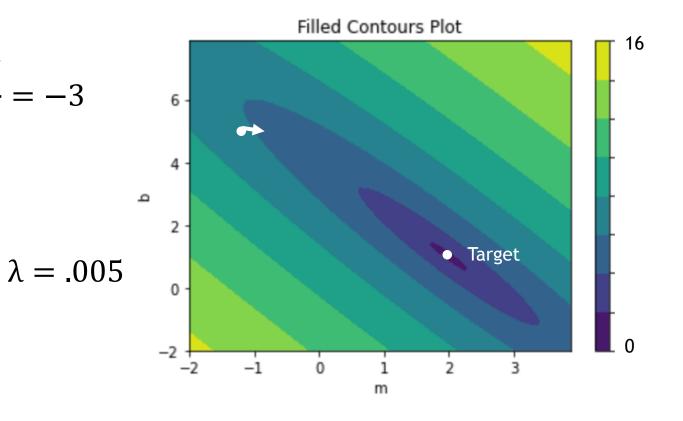
$$b \coloneqq b - \lambda \frac{\partial MSE}{\partial b}$$



$$\frac{\partial MSE}{\partial m} = -7 \qquad \frac{\partial MSE}{\partial b} = -3$$

$$\mathbf{m} := \mathbf{m} - \lambda \, \frac{\partial MSE}{\partial m}$$

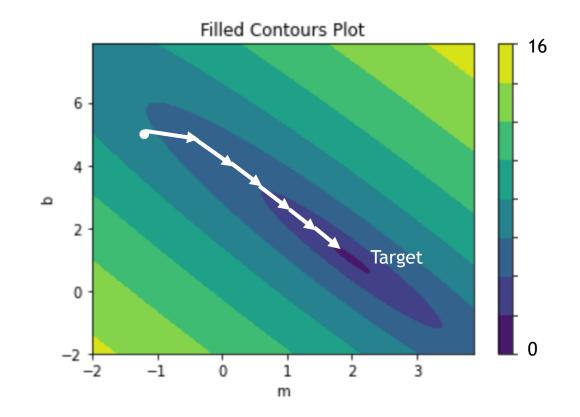
$$b \coloneqq b - \lambda \frac{\partial MSE}{\partial b}$$

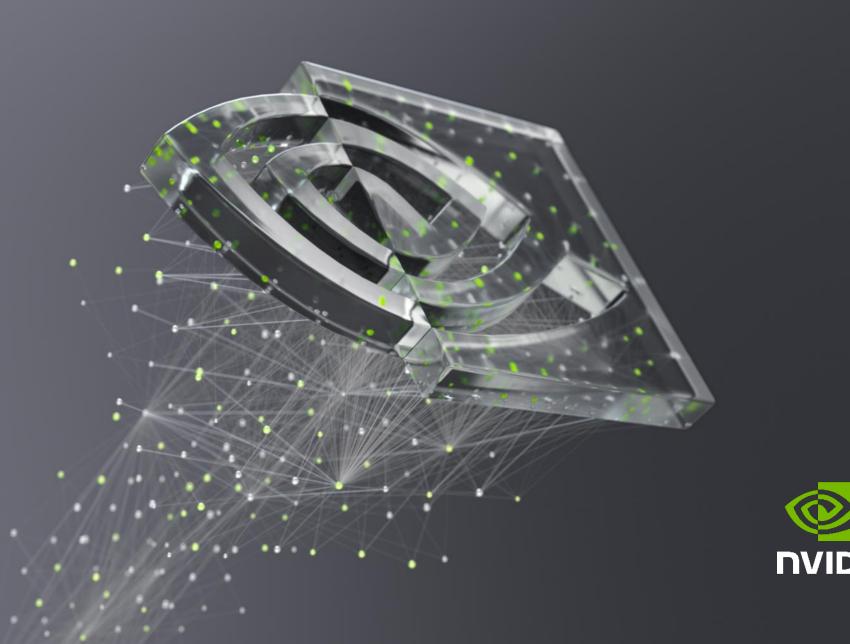




$$m := -1 + 7 \lambda = -0.3$$

$$b := 5 + 3 \lambda = 4.7$$



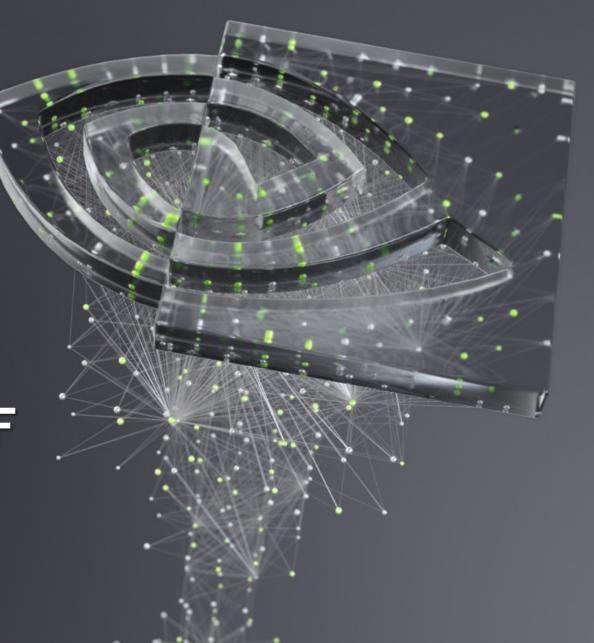






FUNDAMENTALS OF DEEP LEARNING

Part 3: Convolutional Neural Networks



Part 1: An Introduction to Deep Learning Part 2: How a Neural Network Trains Part 3: Convolutional Neural Networks Part 4: Data Augmentation and Deployment Part 5: Pre-trained Models Part 6: Advanced Architectures

RECAP OF THE EXERCISE

Trained a dense neural network model

Training accuracy was high

Validation accuracy was low

Evidence of overfitting













Original Image



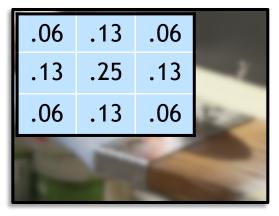




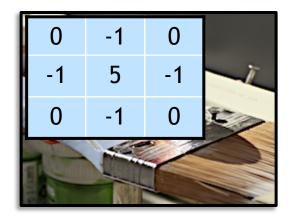






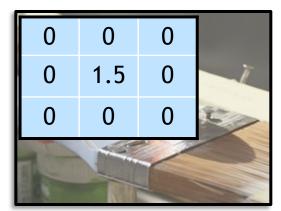




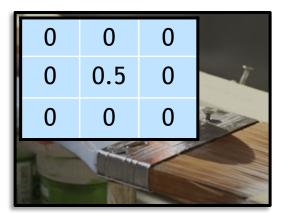


Original Image









Blur Kernel

.06	.13	.06	
.13	.25	.13	>

.06

.06 .13

*

Original Image

1	0	1	1	0	1
0	1	0	0	1	0
0	1	1	1	1	0
0	1	1	1	1	0
1	0	1	1	0	1
1	1	0	0	1	1

Convolved Image



Blur Kernel

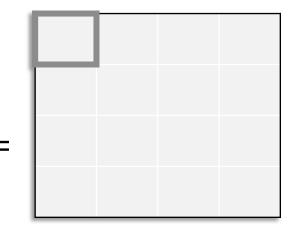
.06	.13	.06
.13	.25	.13
.06	.13	.06

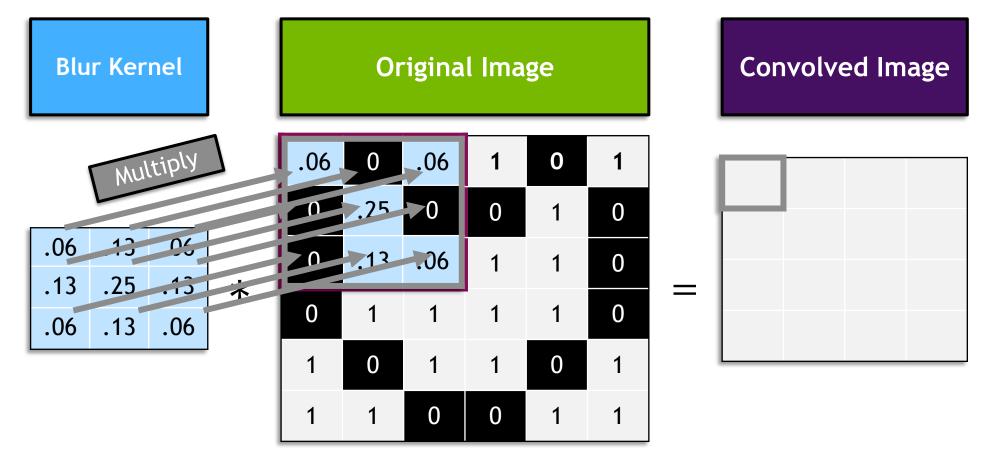
*

Original Image

1	0	1	1	0	1
0	1	0	0	1	0
0	1	1	1	1	0
0	1	1	1	1	0
1	0	1	1	0	1
1	1	0	0	1	1

Convolved Image





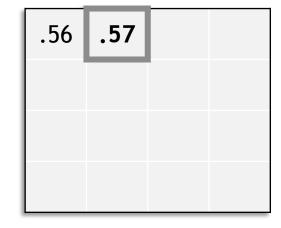


Blur Kernel

.06 .13 .06 .13 .25 .13 * .06 .13 .06 Original Image

1	0	.13	.06	0	1
0	.13	0	0	1	0
0	.06	.13	.06	1	0
0	1	1	1	1	0
1	0	1	1	0	1
1	1	0	0	1	1

Convolved Image



Blur Kernel

.06	.13	.06	
.13	.25	.13	k

.06

.06 .13

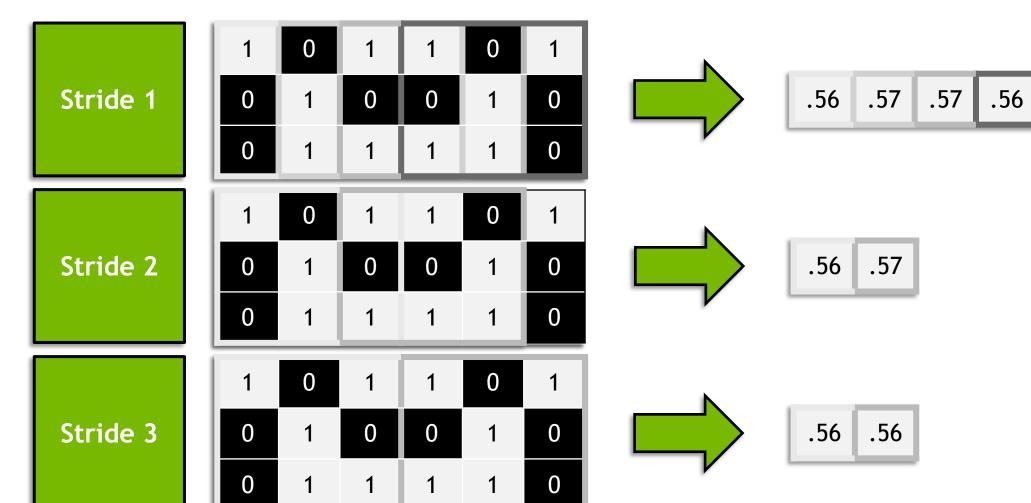
Original Image

1	0	1	1	0	1
0	1	0	0	1	0
0	1	1	1	1	0
0	1	1	1	1	0
1	0	1	1	0	1
1	1	0	0	1	1

Convolved Image

.56	.57	.57	.56
.7	.82	.82	.7
.69	.95	.95	.69
.64	.69	.69	.64

STRIDE



PADDING

Original Image

1 0 1 1 0 1 0 1 0 0 1 0 0 1 1 1 1 0 0 1 1 1 1 0 1 0 1 1 0 1 1 1 0 0 1 1

Zero Padding

0	0	0	0	0	0	0	0
0	1	0	1	1	0	1	0
0	0	1	0	0	1	0	0
0	0	1	1	1	1	0	0
0	0	1	1	1	1	0	0
0	1	0	1	1	0	1	0
0	1	1	0	0	1	1	0
0	0	0	0	0	0	0	0

PADDING

Original Image

Mirror Padding

1	1	0	1	1	0	1	1
1	1	0	1	1	0	1	1
0	0	1	0	0	1	0	0
0	0	1	1	1	1	0	0
0	0	1	1	1	1	0	0
1	1	0	1	1	0	1	1
1	1	1	0	0	1	1	1
1	1	1	0	0	1	1	1



KERNELS AND NEURAL NETWORKS

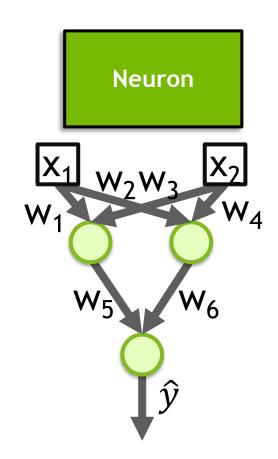
Kernel

W ₁	W ₂	W_3
W_4	W_5	W_6
W ₇	W ₈	W ₉

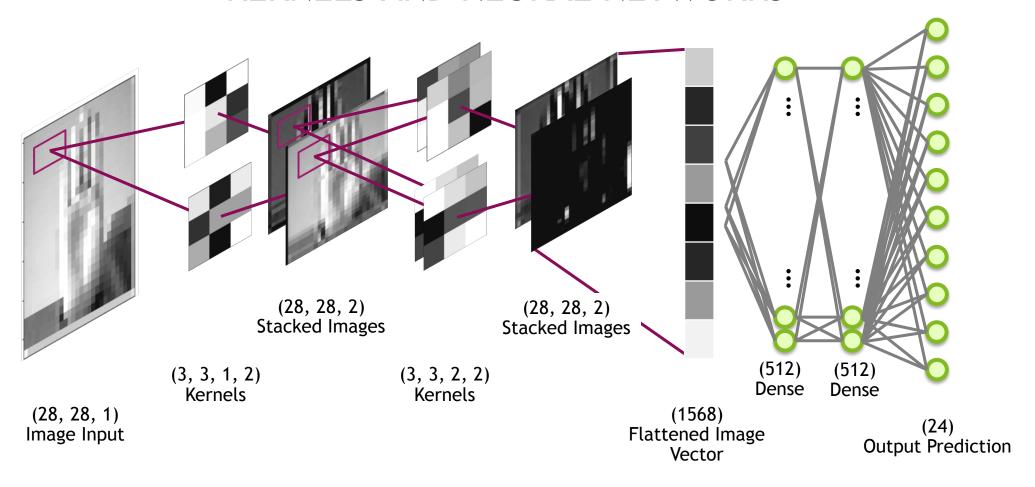
KERNELS AND NEURAL NETWORKS

Kernel

W ₁	W ₂	W ₃
W ₄	W_5	W ₆
W ₇	W ₈	W ₉

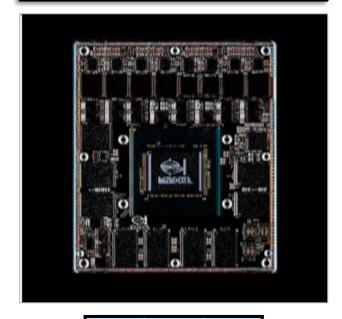


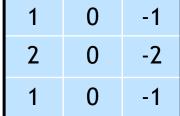
KERNELS AND NEURAL NETWORKS



FINDING EDGES

Vertical Edges



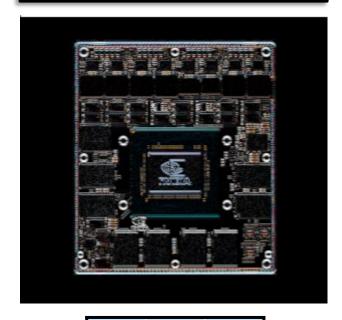


Original Image



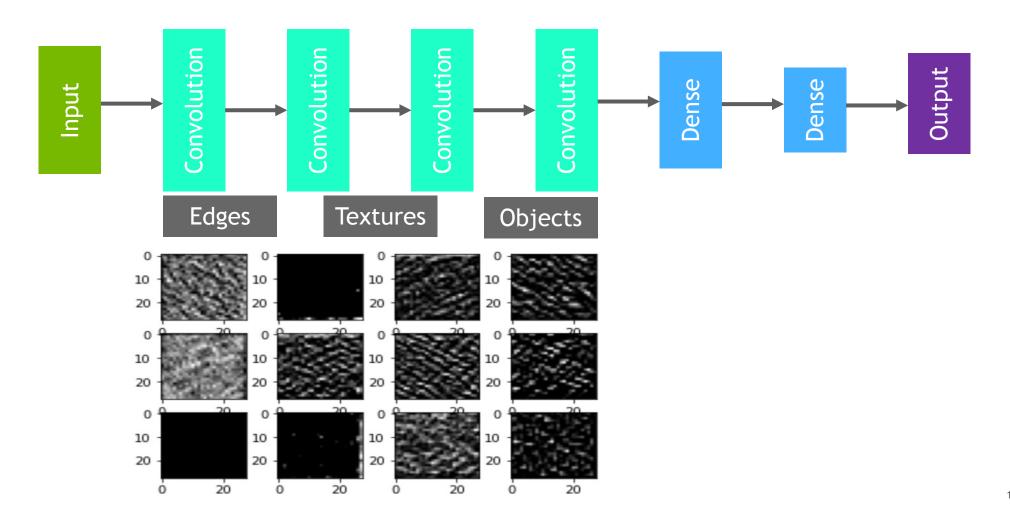
0	0	0
0	1	0
0	0	0

Horizontal Edges



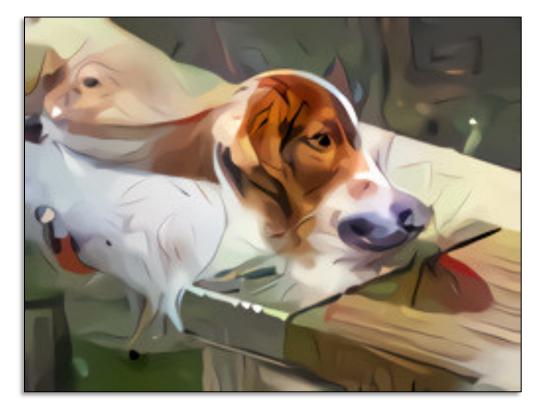
1	2	1
0	0	0
-1	-2	-1

NEURAL NETWORK PERCEPTION



NEURAL NETWORK PERCEPTION

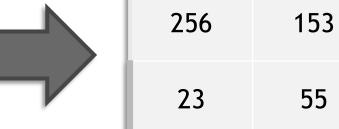




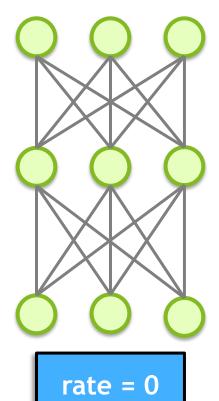


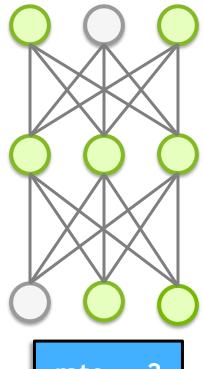
MAX POOLING

110	256	153	67	
12	89	88	43	256
10	15	50	55	23
23	9	49	23	

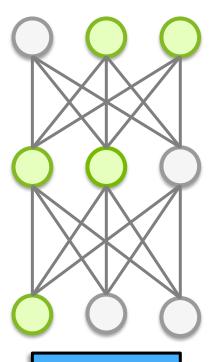


DROPOUT

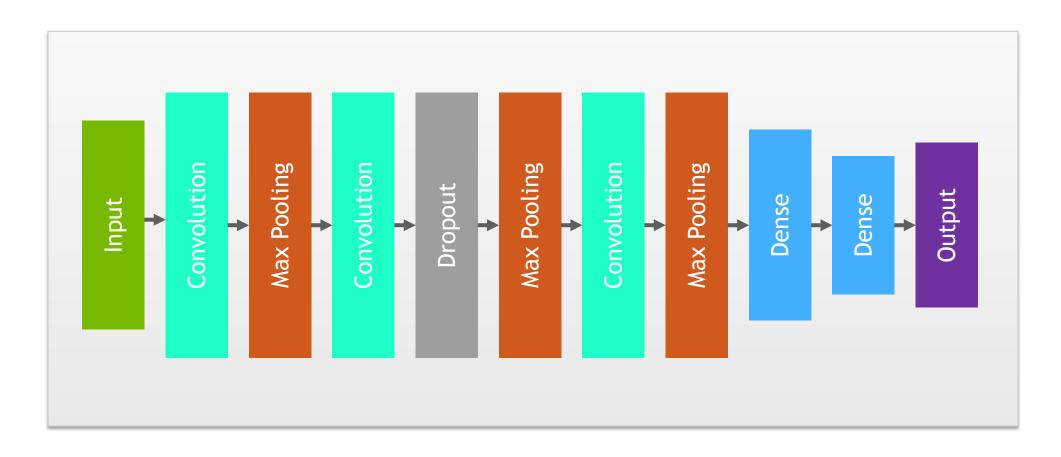




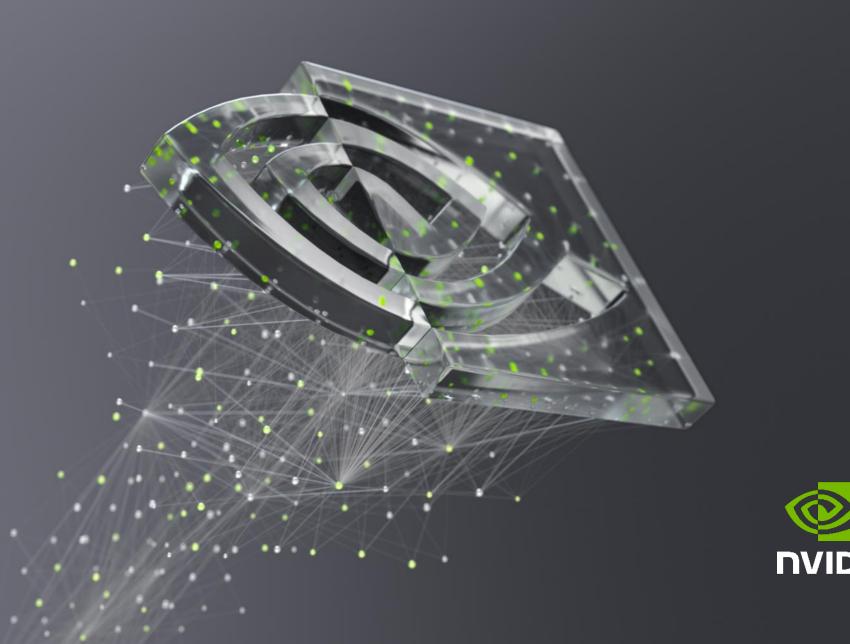




WHOLE ARCHITECTURE





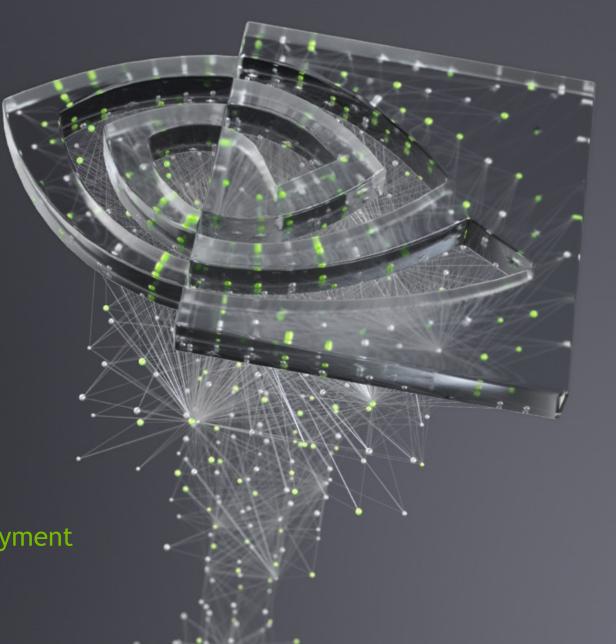






FUNDAMENTALS OF DEEP LEARNING

Part 4: Data Augmentation and Deployment



Part 1: An Introduction to Deep Learning Part 2: How a Neural Network Trains Part 3: Convolutional Neural Networks Part 4: Data Augmentation and Deployment Part 5: Pre-trained Models Part 6: Advanced Architectures

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RECAP OF THE EXERCISE

Analysis

- CNN increased validation accuracy
- Still seeing training accuracy higher than validation

Solution

- Clean data provides better examples
- Dataset variety helps the model generalize









DATA AUGMENTATION

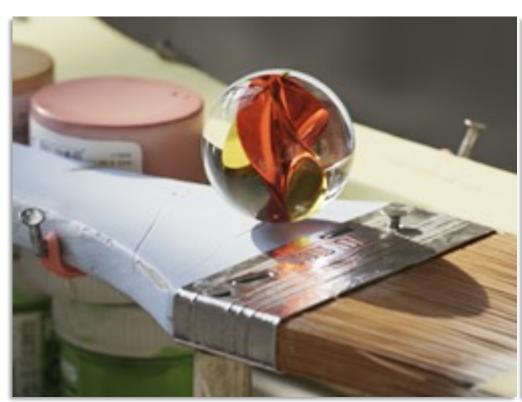




IMAGE FLIPPING

Horizontal Flip



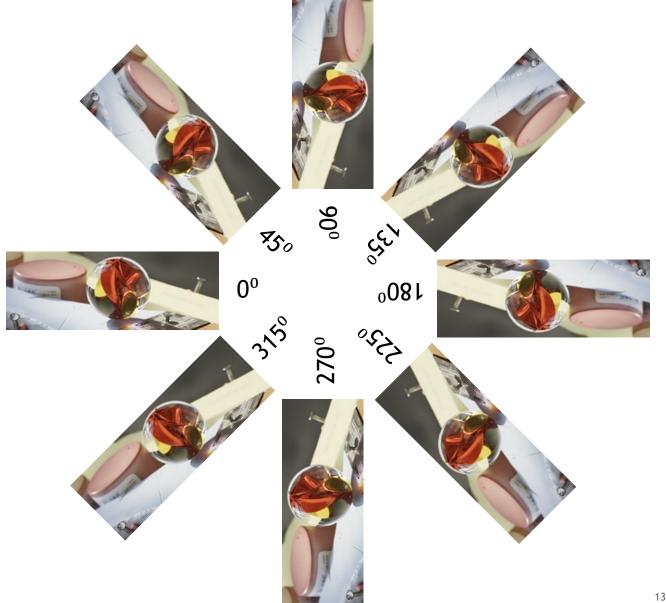






Vertical Flip

ROTATION





ZOOMING

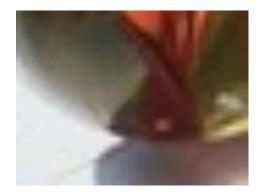


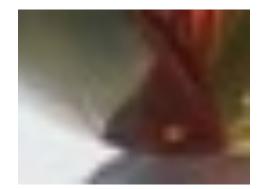


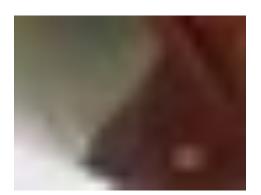












WIDTH AND HEIGHT **SHIFTING**



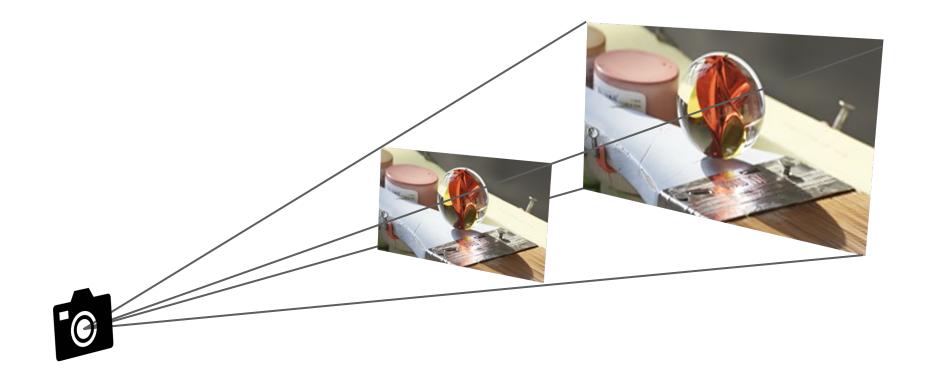








HOMOGRAPHY



BRIGHTNESS





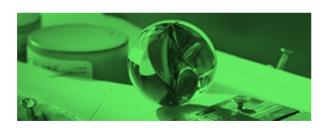






CHANNEL SHIFTING









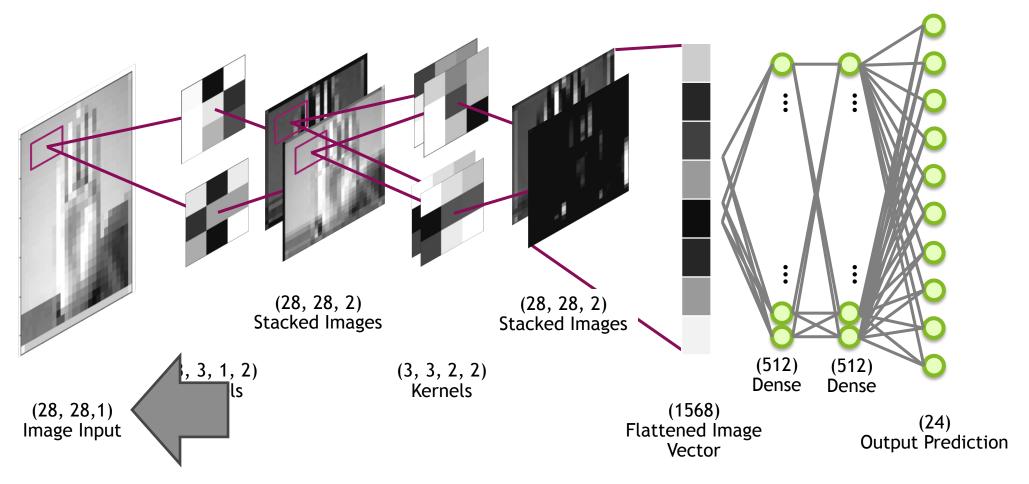








MODEL DEPLOYMENT



MODEL DEPLOYMENT

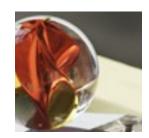
Training
Batch Input











Convolution

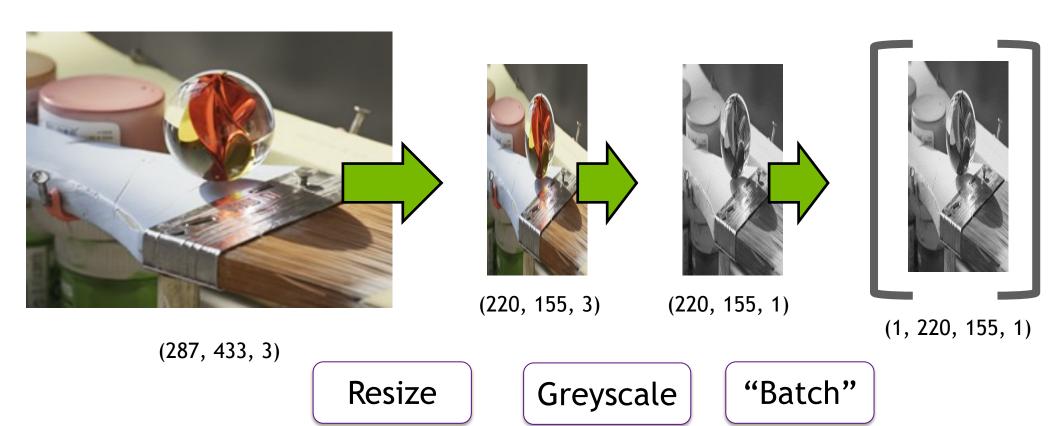
Max Pooling

•••

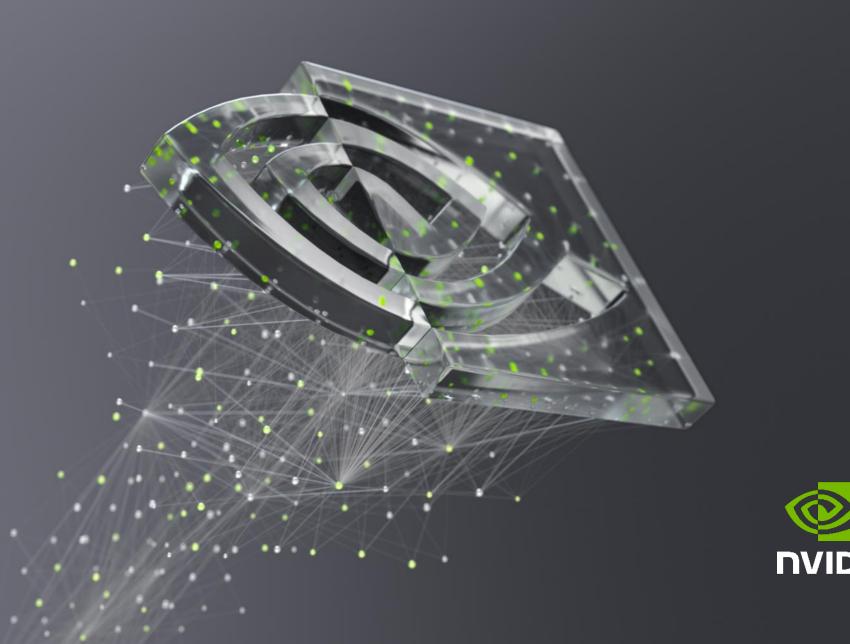




MODEL DEPLOYMENT





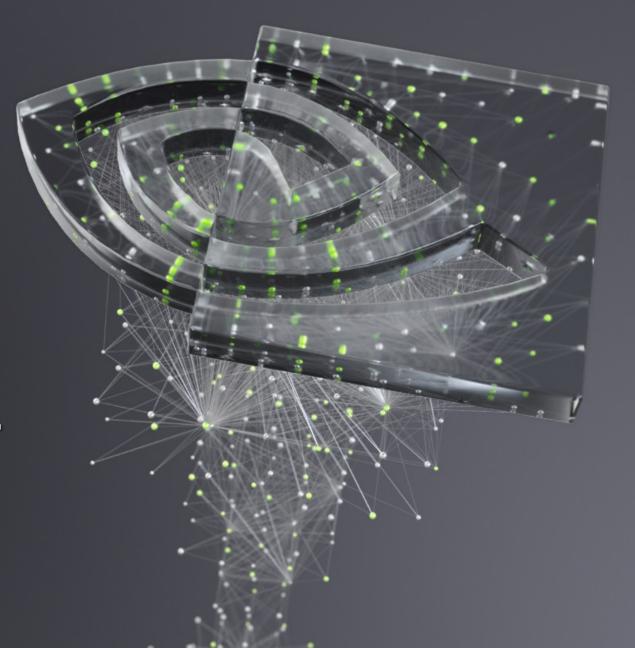






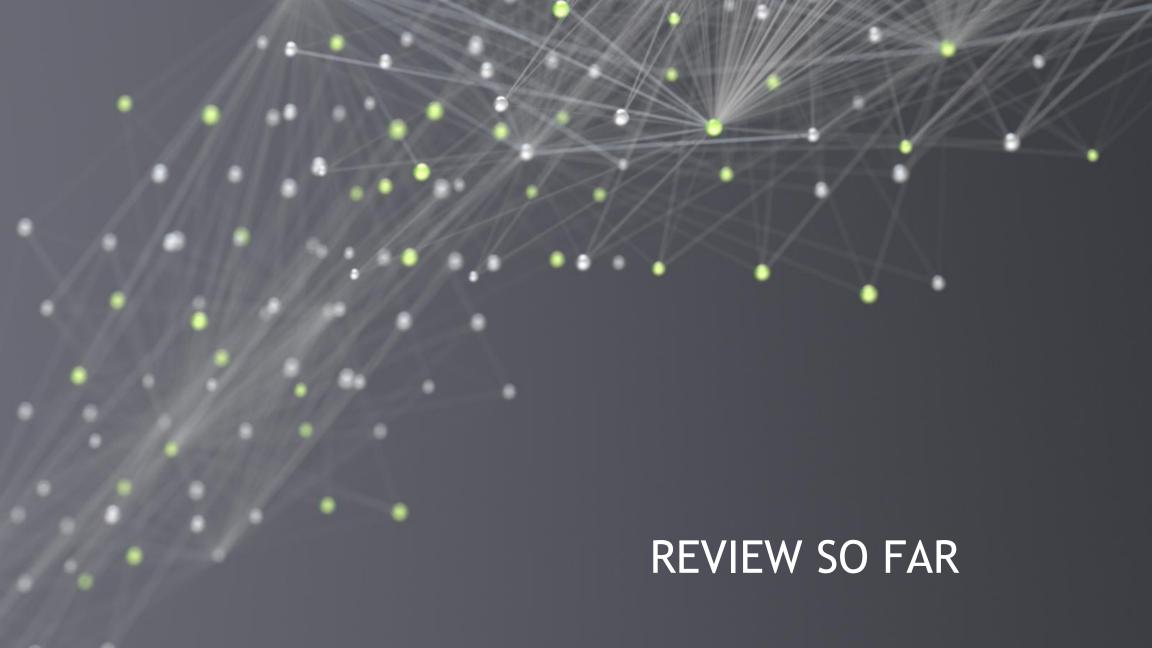
FUNDAMENTALS OF DEEP LEARNING

Part 5: Pre-trained Models



Part 1: An Introduction to Deep Learning Part 2: How a Neural Network Trains Part 3: Convolutional Neural Networks Part 4: Data Augmentation and Deployment Part 5: Pre-trained Models Part 6: Advanced Architectures

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REVIEW SO FAR



- Learning Rate
- Number of Layers
- Neurons per Layer
- Activation Functions
- Dropout
- Data



PRE-TRAINED MODELS

TensorFlow Hub





PYTORCH HUB

PRE-TRAINED MODELS

VERY DEEP CONVOLUTIONAL NETWORKS FOR LARGE-SCALE IMAGE RECOGNITION

Karen Simonyan* & Andrew Zisserman+

Visual Geometry Group, Department of Engineering Science, University of Oxford {karen, az}@robots.ox.ac.uk



THE NEXT CHALLENGE

An Automated Doggy Door











THE CHALLENGE AFTER

An Automated Presidential Doggy Door

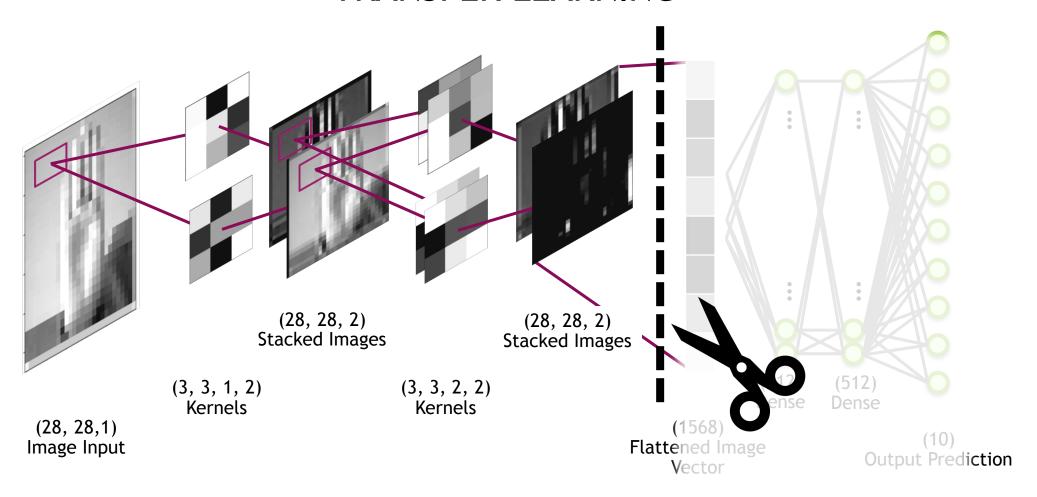


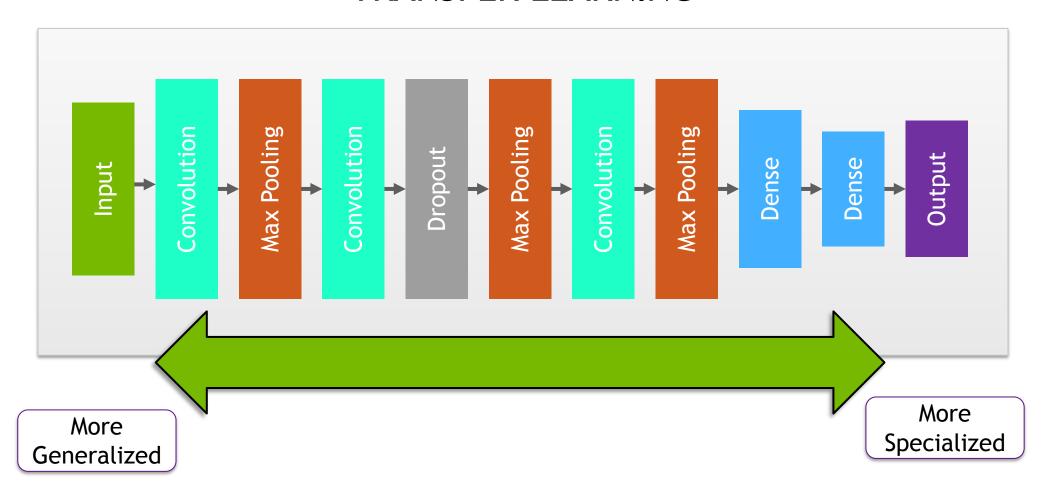












Freezing the Model?

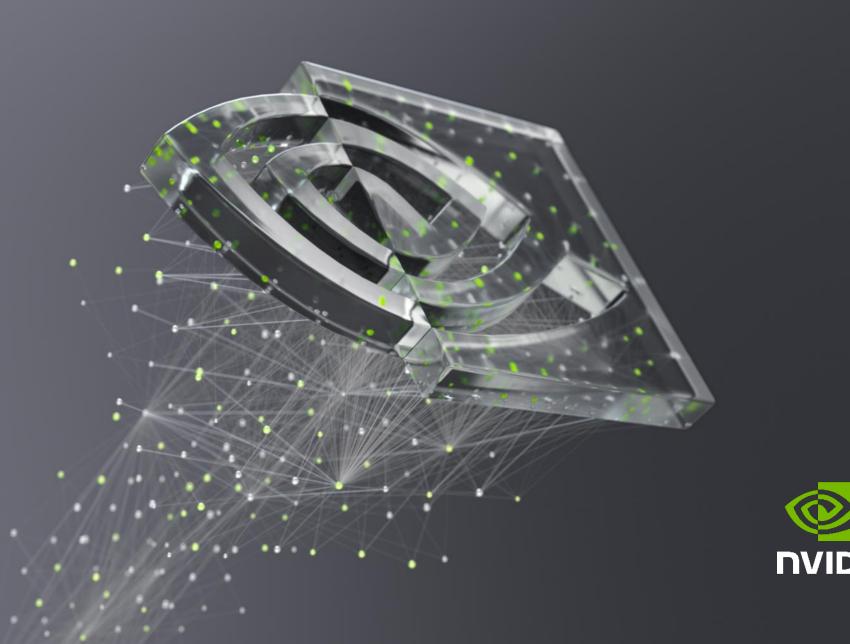










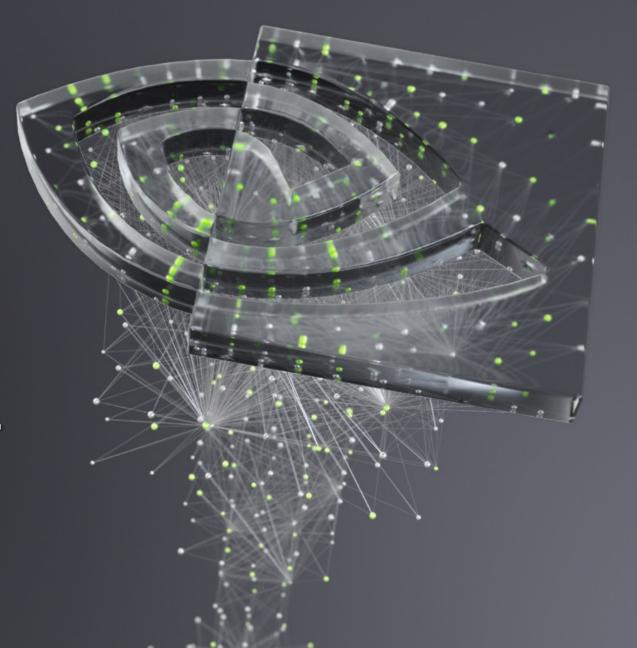






FUNDAMENTALS OF DEEP LEARNING

Part 6: Advanced Architectures



Part 1: An Introduction to Deep Learning Part 2: How a Neural Network Trains Part 3: Convolutional Neural Networks Part 4: Data Augmentation and Deployment Part 5: Pre-trained Models Part 6: Advanced Architectures



FIELDS OF AI



Computer Vision

Optometry



Natural Language Processing

Linguistics



Reinforcement Learning

- Game Theory
- Psychology



Anomaly Detection

- Security
- Medicine

FIELDS OF AI



Computer Vision

Optometry



Natural Language Processing

Linguistics



Reinforcement Learning

- Game Theory
- Psychology



Anomaly Detection

- Security
- Medicine

FIELDS OF AI



Computer Vision

Optometry



Natural Language Processing

Linguistics



Reinforcement Learning

- Game Theory
- Psychology



Anomaly Detection

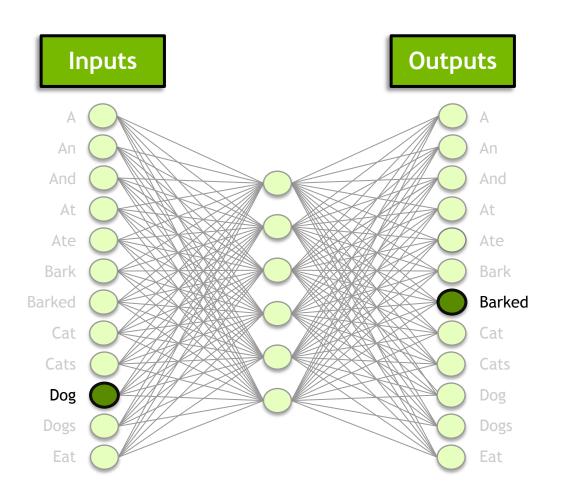
- Security
- Medicine



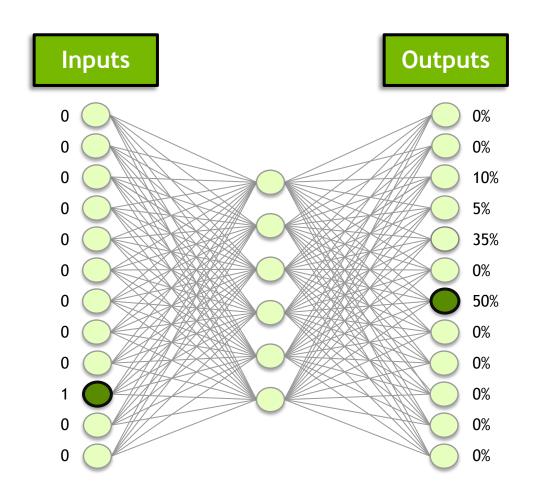
"A dog barked at a cat."

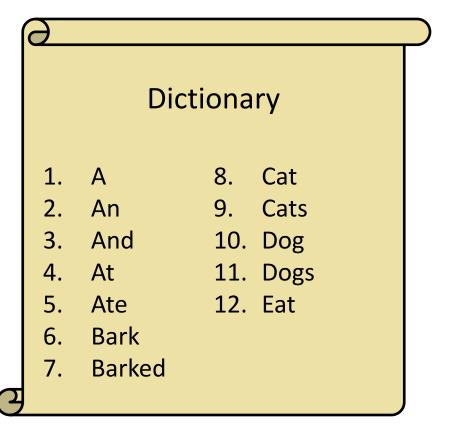
[1, 10, 7, 4, 1, 8]

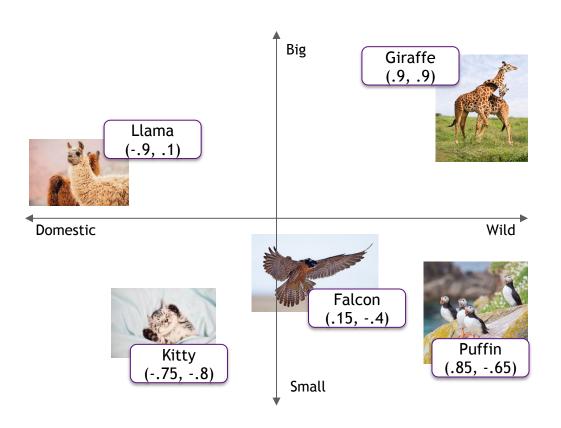




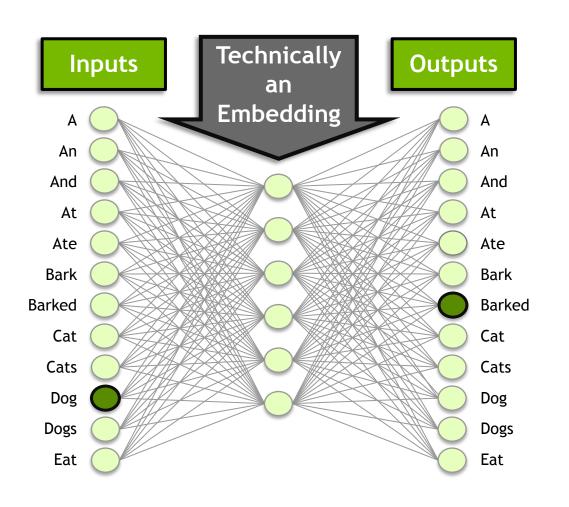






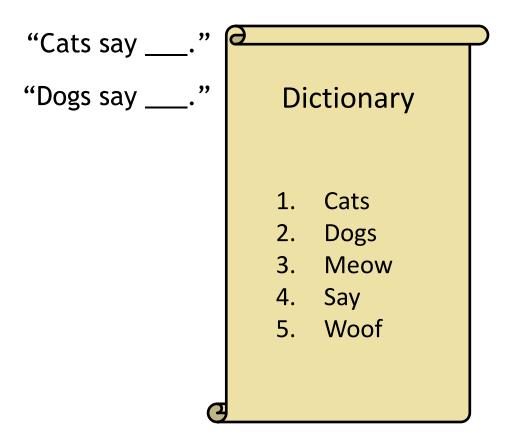


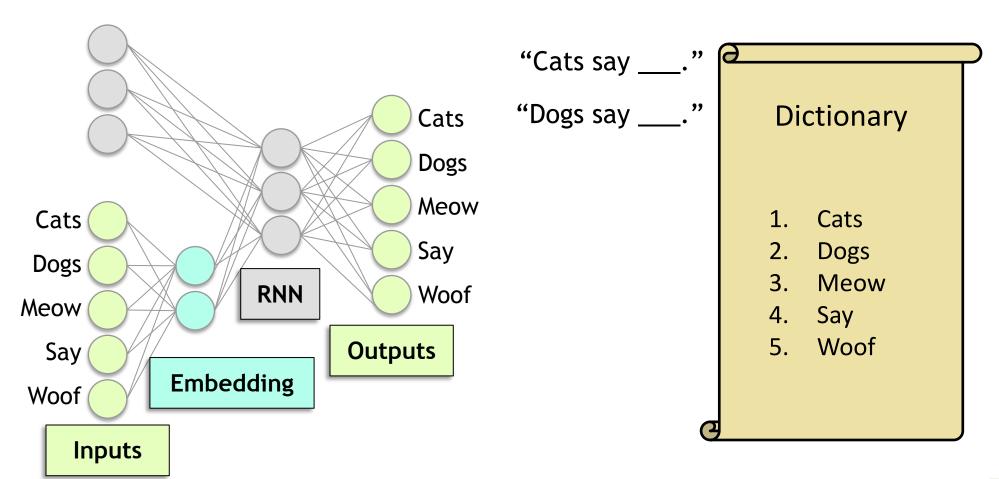


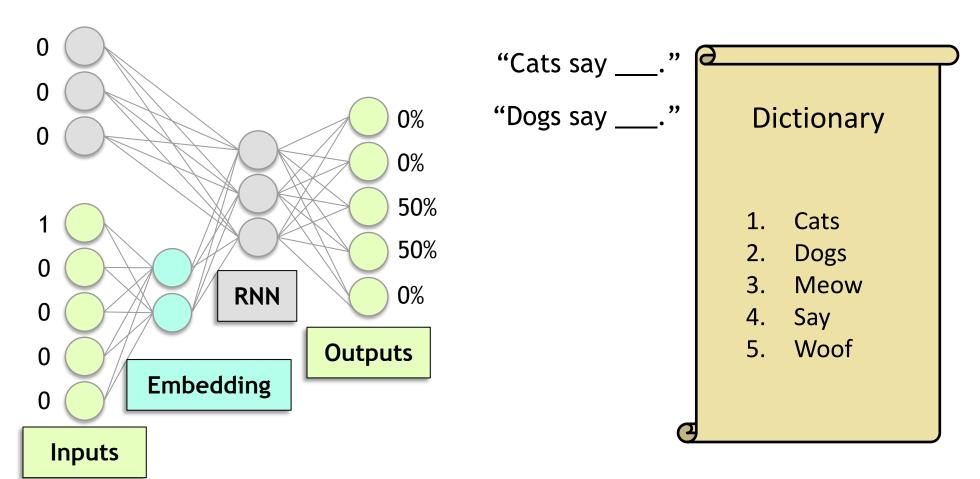


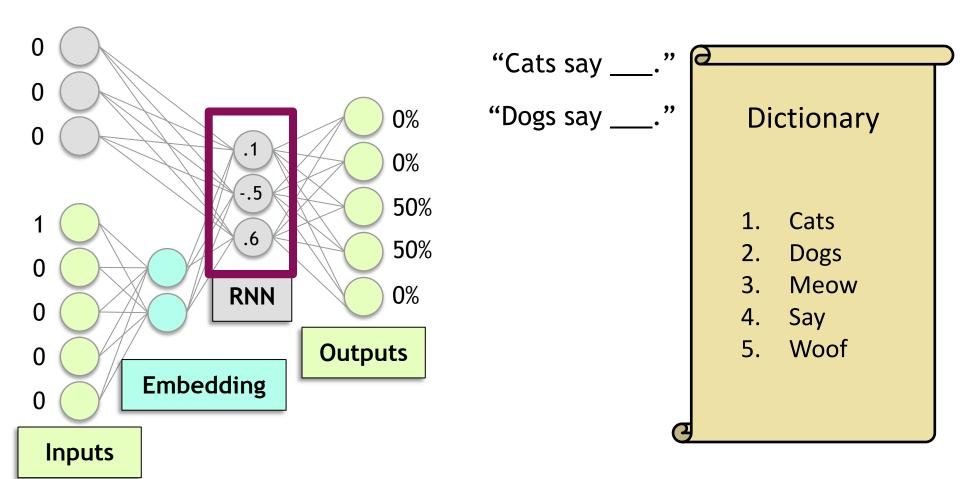


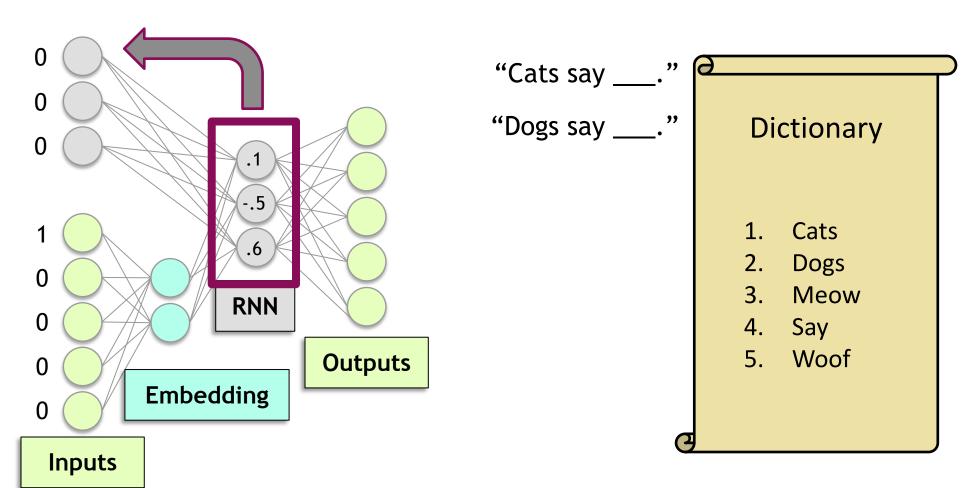


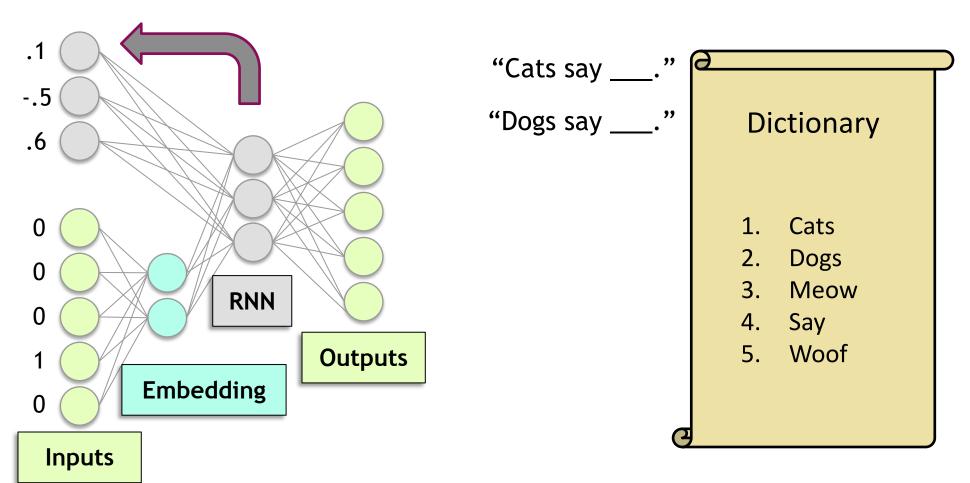




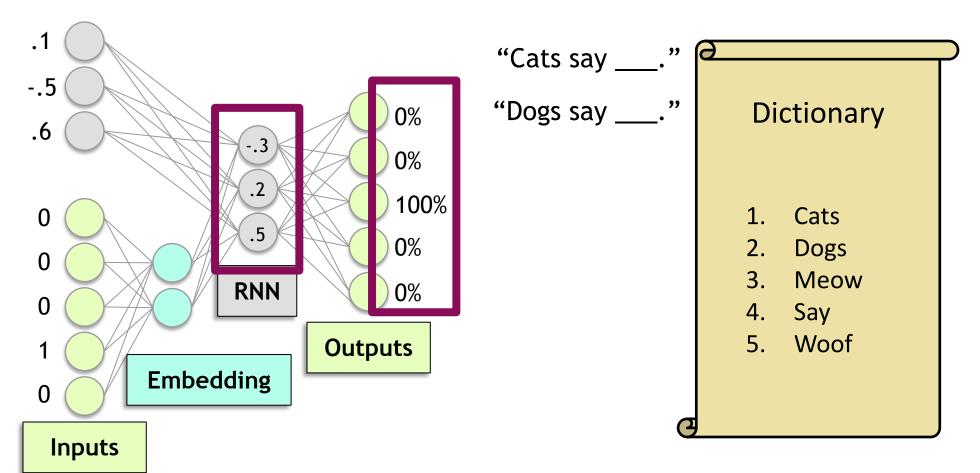




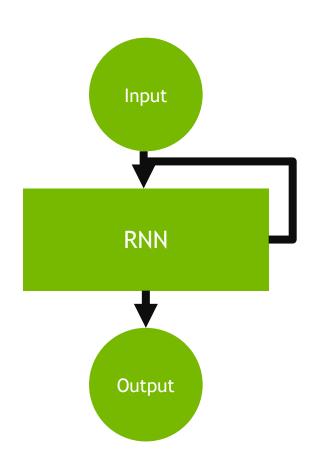


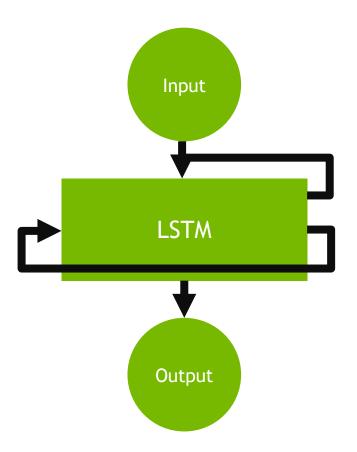


RECURRENT NEURAL NETWORKS



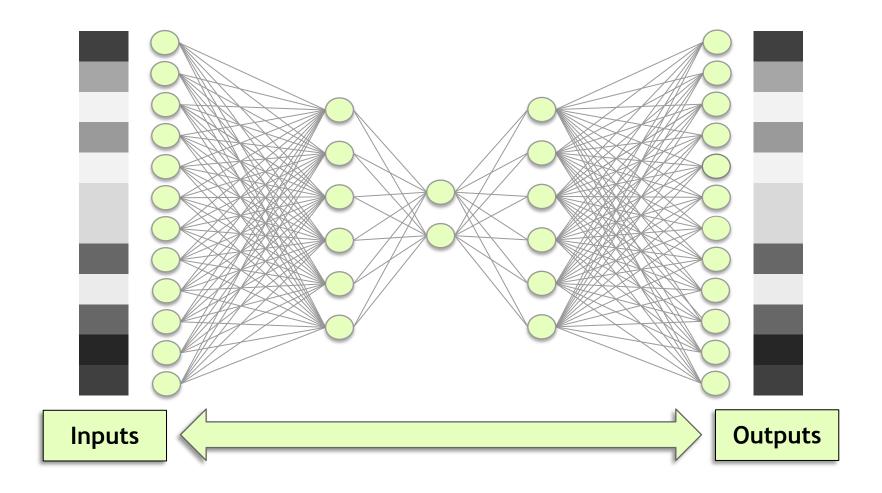
RECURRENT NEURAL NETWORKS



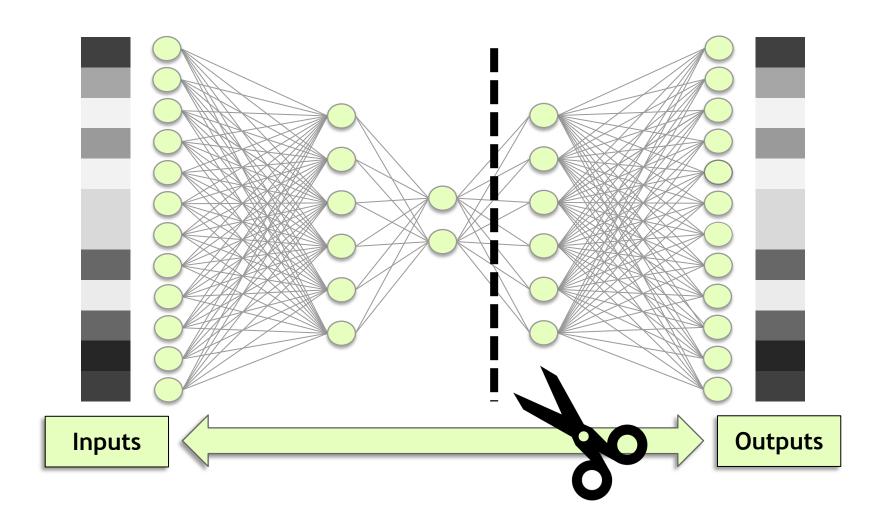




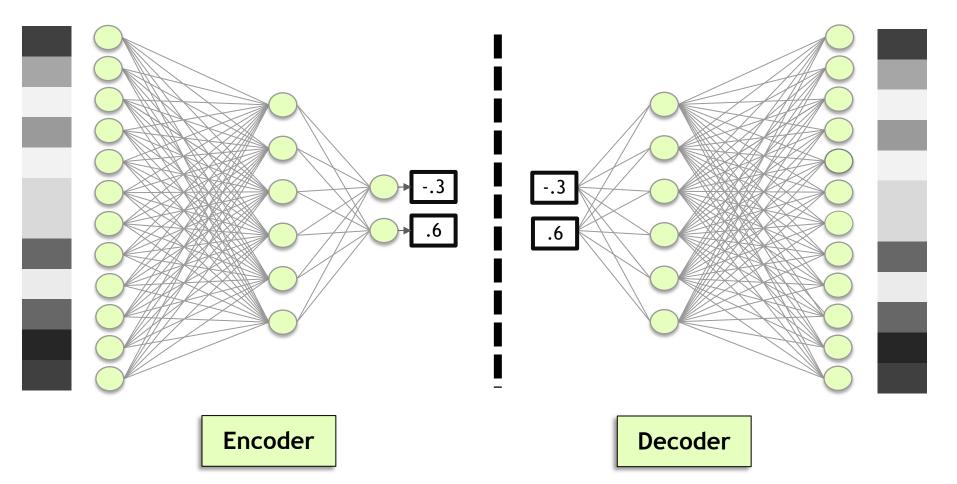
AUTOENCODERS



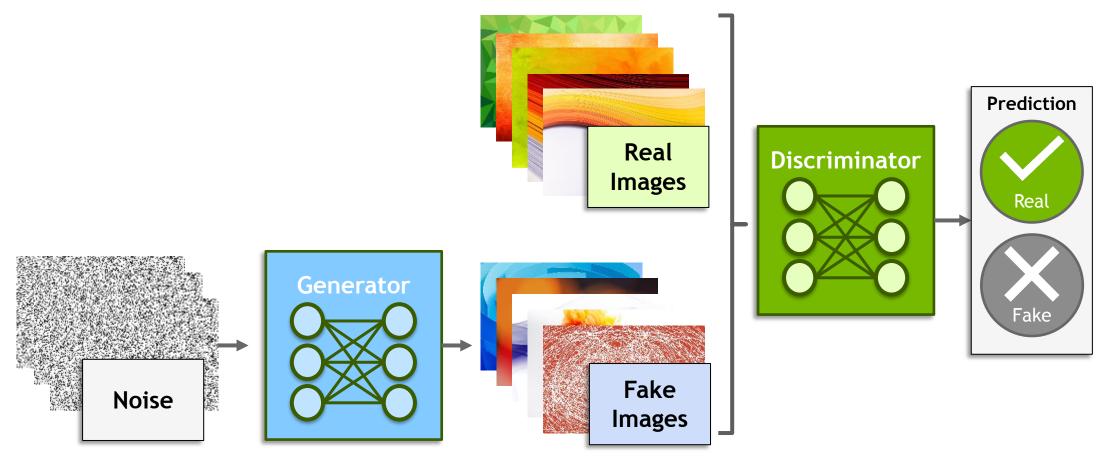
AUTOENCODERS



AUTOENCODERS

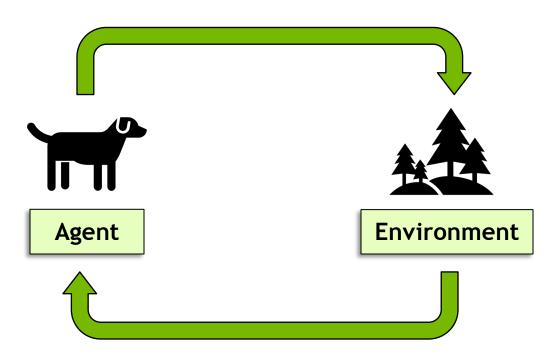


GENERATIVE ADVERSARIAL NETWORKS (GANS)



REINFORCEMENT LEARNING







ENABLING PORTABILITY WITH NGC CONTAINERS

Extensive

- Diverse range of workloads and industry specific use cases

Optimized

- DL containers updated monthly
- Packed with latest features and superior performance

Secure & Reliable

- Scanned for vulnerabilities and crypto
- Tested on workstations, servers, & cloud instances

Scalable

Supports multi-GPU & multi-node systems

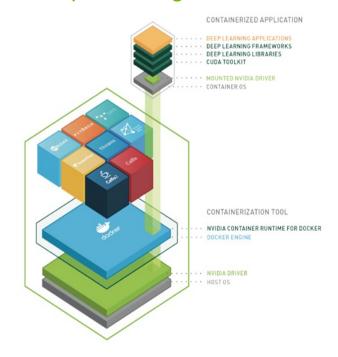
Designed for Enterprise & HPC

Supports Docker, Singularity & other runtimes

Run Anywhere

- Bare metal, VMs, Kubernetes
- x86, ARM, POWER
- Multi-cloud, on-prem, hybrid, edge

NGC Deep Learning Containers











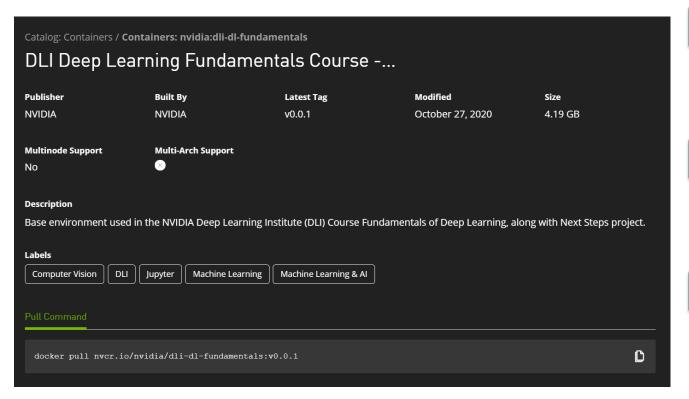








NEXT STEPS FOR THIS CLASS



Step 1 Sign up for NGC

https://docs.nvidia.com/dgx/ng c-registry-for-dgx-userguide/index.html

Step 2 Visit NGC Catalog

https://catalog.ngc.nvidia.com/ orgs/nvidia/containers/dli-dl**fundamentals**

Step 3 Pull and Run Container

Visit localhost:8888 to check out a JupyterLab environment with a Next Steps Project



COPYING ROCKET SCIENCE





