

# MODULE SIX: LOOP OPTIMIZATIONS

Dr. Volker Weinberg | LRZ

# LOOP OPTIMIZATIONS

- Majority of program runtime is spent in loops
- Every loop can execute in a very different way
- Using OpenACC loop optimization, we can speed-up our most time-consuming portions of code

# SAMPLE LOOP CODE

## Matrix multiplication

- Our code is a 3-Dimensional Matrix Multiplication code
- The code allows for many different levels and types of parallelism, and works well with all of our loop clauses

```
for( i = 0; i < size; i++ )  
  for( j = 0; j < size; j++ )  
    for( k = 0; k < size; k++ )  
      c[i][j] += a[i][k] * b[k][j];
```

# SAMPLE LOOP CODE

## Matrix multiplication

- Our code is a 3-Dimensional Matrix Multiplication code
- The code allows for many different levels and types of parallelism, and works well with all of our loop clauses

```
do k = 1, size
  do j = 1, size
    do i = 1, size
      c(i,j) = c(i,j) + a(i,k)*b(k,j)
    end do
  end do
end do
```

# PARALLELIZING LOOPS

# AUTO CLAUSE

- The **auto** clause tells the compiler to decide whether or not the loop is parallelizable
- The auto clause can be very useful when you are unsure of whether or not a loop is safe to parallelize

```
#pragma acc parallel loop auto
for( i = 0; i < size; i++ )
    for( j = 0; j < size; j++ )
        for( k = 0; k < size; k++ )
            c[i][j] += a[i][k] * b[k][j];
```

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do k = 1, size
  do j = 1, size
    do i = 1, size
      c(i,j) = c(i,j) + a(i,k)*b(k,j)
    end do
  end do
end do
```

# AUTO CLAUSE

- When using the **kernels directive**, the auto clause is **implied**
- This means that you do not need to include the auto clause when using the kernels directive
- However, the auto clause can be very useful when using the **parallel directive**

```
#pragma acc kernels loop auto  
for( i = 0; i < size; i++ )  
    for( j = 0; j < size; j++ )  
        for( k = 0; k < size; k++ )  
            c[i][j] += a[i][k] * b[k][j];
```



# INDEPENDENT CLAUSE

- The **independent** clause asserts to the compiler that the loop is parallelizable
- This will overwrite any decision that the compiler makes about the loop
- Adding the independent clause could force the compiler to parallelize a non-parallel loop
- Allows the programmer to force parallelism when using the kernels directive

```
#pragma acc kernels loop independent
for( i = 0; i < size; i++ )
    for( j = 0; j < size; j++ )
        for( k = 0; k < size; k++ )
            c[i][j] += a[i][k] * b[k][j];
```

# INDEPENDENT CLAUSE

- When using the **parallel directive**, the independent clause is **implied**
- With the parallel directive, the programmer is determining which loops are parallelizable and thus the independent clause is not needed

```
#pragma acc parallel loop independent
for( i = 0; i < size; i++ )
    for( j = 0; j < size; j++ )
        for( k = 0; k < size; k++ )
            c[i][j] += a[i][k] * b[k][j];
```

# LOOP CORRECTNESS

# SEQ CLAUSE

- The **seq** clause (short for sequential) will tell the compiler to run the loop sequentially
- In the sample code, the compiler will parallelize the outer loops across the parallel threads, but each thread will run the inner-most loop sequentially
- The compiler may automatically apply the seq clause to loops that have too many dimensions

```
#pragma acc parallel loop
for( i = 0; i < size; i++ )
  #pragma acc loop
  for( j = 0; j < size; j++ )
    #pragma acc loop seq
    for( k = 0; k < size; k++ )
      c[i][j] += a[i][k] * b[k][j];
```

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!$acc parallel loop
do k = 1, size
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    !$acc loop seq
    do i = 1, size
      c(i,j) = c(i,j) + a(i,k)*b(k,j)
    end do
  end do
end do
```

# PRIVATE AND FIRSTPRIVATE CLAUSES

- The **private** clause allows the programmer to define a list of variables as “thread-private”.
- Each thread will be given a private copy of every variable in the comma-separated list
- **firstprivate** is like private except that the private values are initialized to the same value used on the host. **private** variables are uninitialized.

```
double tmp[3];  
  
#pragma acc kernels loop private(tmp[0:3])  
for( i = 0; i < size; i++ )  
{  
    tmp[0] = <value>;  
    tmp[1] = <value>;  
    tmp[2] = <value>;  
}  
  
// note that the host value of “tmp”  
// remains unchanged.
```

# PRIVATE AND FIRSTPRIVATE CLAUSES

- Variables in **private** or **firstprivate** clause are private to the loop level on which the clause appears.
- Private variables on an outer loop are shared within inner loops.

```
double tmp[3];

#pragma acc kernels loop private(tmp[0:3])
for( i = 0; i < size; i++ ) {
    // the tmp array is private to each iteration
    // of the outer loop
    tmp[0] = <value>;
    tmp[1] = <value>;
    tmp[2] = <value>;
    #pragma acc loop
    for ( j = 0; j < size2; j++ ) {
        // but tmp is shared amongst the threads
        // in the inner loop
        array[i][j] = tmp[0]+tmp[1]+tmp[2];
    }
}
```

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```
real :: tmp(3)

!$acc kernels loop private(tmp(0:3))
do i = 1, size
    tmp(0) = <value>
    tmp(1) = <value>
    tmp(2) = <value>
end do
!$acc end kernels

! note that the host value of “tmp”
! remains unchanged.
```



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  tmp(0) = <value>
  tmp(1) = <value>
  tmp(2) = <value>
  !$acc loop
  do j = 1, size2
    ! but tmp is shared amongst the threads
    ! in the inner loop
    array(i,j) = tmp(0)+tmp(1)+tmp(2)
  end do
end do
!$acc end kernels
```

# LOOP OPTIMIZATIONS

# COLLAPSE CLAUSE

- `collapse( N )`
- Combine the next N tightly nested loops
- Can turn a multidimensional loop nest into a single-dimension loop
- This can be extremely useful for increasing memory locality, as well as creating larger loops to expose more parallelism

```
#pragma acc parallel loop collapse(2)
for( i = 0; i < size; i++ )
    for( j = 0; j < size; j++ )
        double tmp = 0.0f;
        #pragma acc loop reduction(+:tmp)
        for( k = 0; k < size; k++ )
            tmp += a[i][k] * b[k][j];
        c[i][j] = tmp;
```

# COLLAPSE CLAUSE

**collapse( 2 )**

(0,0)	(0,1)	(0,2)	(0,3)
(1,0)	(1,1)	(1,2)	(1,3)
(2,0)	(2,1)	(2,2)	(2,3)
(3,0)	(3,1)	(3,2)	(3,3)

```
#pragma acc parallel loop collapse(2)
for( i = 0; i < 4; i++ )
  for( j = 0; j < 4; j++ )
    array[i][j] = 0.0f;
```

# TILE CLAUSE

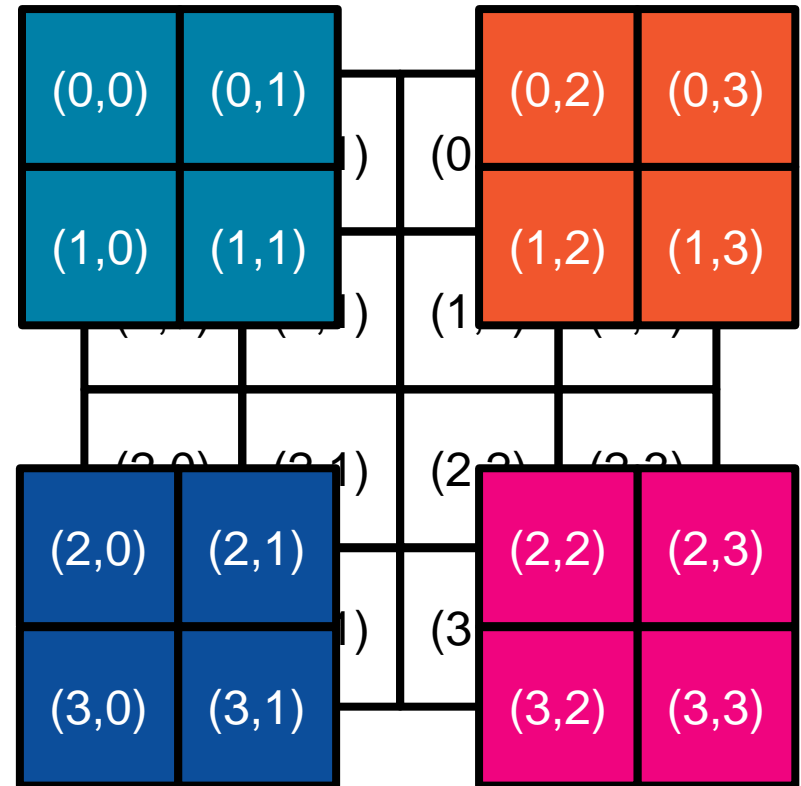
- **tile ( x , y , z , ... )**
- Breaks multidimensional loops into “tiles” or “blocks”
- Can increase data locality in some codes
- Will be able to execute multiple “tiles” simultaneously

```
#pragma acc kernels loop tile(32, 32)
for( i = 0; i < size; i++ )
  for( j = 0; j < size; j++ )
    for( k = 0; k < size; k++ )
      c[i][j] += a[i][k] * b[k][j];
```

# TILE CLAUSE

```
#pragma acc kernels loop tile(2,2)
for(int x = 0; x < 4; x++){
    for(int y = 0; y < 4; y++){
        array[x][y]++;
    }
}
```

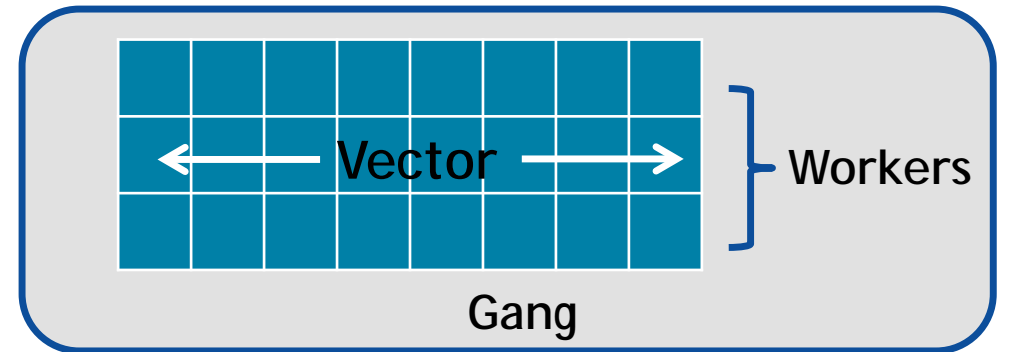
tile ( 2 , 2 )



# GANG WORKER VECTOR

# GANG WORKER VECTOR

- Gang / Worker / Vector defines the various levels of parallelism we can achieve with OpenACC
- This parallelism is most useful when parallelizing multi-dimensional loop nests
- OpenACC allows us to define a generic Gang / Worker / Vector model that will be applicable to a variety of hardware, but we will focus a little bit on a GPU specific implementation





# GANG WORKER VECTOR

- When paralleling our loops, the highest level of parallelism is **gang level parallelism**
- When encountering either the kernels or parallel directive, multiple gangs will be generated, and loop iterations will be spread across the gangs
- These gangs are completely independent of each other, and there is no way for the programmer to know exactly how many gangs are running at a given time
- In many architectures, the gangs have completely separate (or private) memory



# GANG WORKER VECTOR

- In our code example, we see that we are applying the **gang** clause to an outer-loop
- This means that the outer-loop iterations will be split across some number of gangs
- These gangs will then execute in parallel with each other
- Whenever a parallel compute region is encountered, some number of gangs will be created
- The programmer is able to specify exactly how many gangs to create



```
#pragma acc parallel loop gang
for( i = 0; i < N; i++ )
    for( j = 0; j < M; j++ )
        < loop code >
```

# GANG WORKER **VECTOR**

- A **vector** is the lowest level of parallelism
- Every gang will have **at least 1 vector**
- A vector has the ability to **run a single instruction on multiple data elements**
- Many different architectures can implement vectors in different ways, however, OpenACC allows for us to define them in a general, non-hardware-specific way



# GANG WORKER **VECTOR**

- In our code example, the inner-loop iterations will be evenly divided across a vector
- This means that those loop iterations will be executing in parallel with one-another
- Any loop that is **inside** of our vector loop cannot be parallelized further



```
#pragma acc parallel loop gang
for( i = 0; i < N; i++ )
  #pragma acc loop vector
  for( j = 0; j < M; j++ )
    < loop code >
```

# GANG **WORKER** VECTOR

- The **worker clause** is a way for the programmer to have **multiple vectors** within a gang
- The primary use of the worker clause is to split up one large vector into multiple smaller vectors
- This can be useful when our inner parallel loops are very small, and will not benefit from having a large vector



# GANG **WORKER** VECTOR

- In our sample code, we apply both gang and worker level parallelism to our outer-loop
- The main difference this creates for our code is that we can now have smaller vectors running the inner loop
- This will most likely improve performance **if** the inner loop is relatively small



```
#pragma acc parallel loop gang worker
for( i = 0; i < N; i++ )
  #pragma acc loop vector
  for( j = 0; j < M; j++ )
    < loop code >
```

# PARALLEL DIRECTIVE SYNTAX

- When using the parallel directive, you may define the number of gangs/workers/vectors with **num\_gangs(N)**, **num\_workers(M)**, **vector\_length(Q)**
- Then, you may define where they belong in the loops using **gang**, **worker**, **vector**

```
#pragma acc parallel num_gangs(2) \
num_workers(2) vector_length(32)
{
    #pragma acc loop gang worker
    for(int x = 0; x < 4; x++){
        #pragma acc loop vector
        for(int y = 0; y < 32; y++){
            array[x][y]++;
        }
    }
}
```

# PARALLEL DIRECTIVE SYNTAX

- You may also apply gang/worker/vector when using the parallel loop construct

```
#pragma acc parallel loop num_gangs(2) num_workers(2) \  
    vector_length(32) gang worker  
for(int x = 0; x < 4; x++){  
    #pragma acc loop vector  
    for(int y = 0; y < 32; y++){  
        array[x][y]++;  
    }  
}
```



# KERNELS DIRECTIVE SYNTAX

- When using the kernels directive, the process is somewhat simplified
- You may define the location and number by using **gang(N)**, **worker(M)**, **vector(Q)**
- You may also define gang, worker, and vector using the same method as with the parallel directive
- If you do not specify a number, the compiler will decide one

```
#pragma acc kernels loop gang(2) worker(2)
for(int x = 0; x < 4; x++){
    #pragma acc loop vector(32)
    for(int y = 0; y < 32; y++){
        array[x][y]++;
    }
}
```

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- When using the kernels directive, the process is somewhat simplified
- You may define the location and number by using **gang(N)**, **worker(M)**, **vector(Q)**
- You may also define gang, worker, and vector using the same method as with the parallel directive
- If you do not specify a number, the compiler will decide one
- Each loop nest can have different values for gang, worker, and vector

```
#pragma acc kernels
{
    #pragma acc loop gang(2) worker(2)
    for(int x = 0; x < 4; x++){
        #pragma acc loop vector(32)
        for(int y = 0; y < 32; y++){
            array[x][y]++;
        }
    }

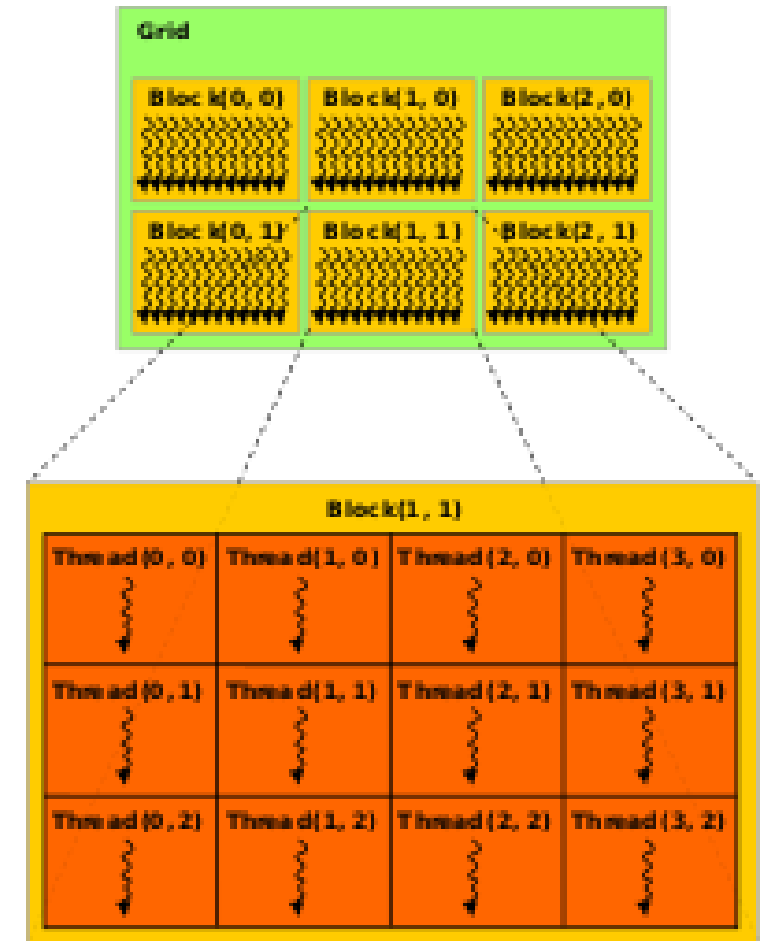
    #pragma acc loop gang(4) worker(4)
    for(int x = 0; x < 16; x++){
        #pragma acc loop vector(16)
        for(int y = 0; y < 16; y++){
            array2[x][y]++;
        }
    }
}
```

# WARPS

- So far we have been using a very small number of gangs/worker/vectors, simply because they're easier to understand
- When actually programming, the number of gangs/worker/vectors will be much larger
- When specifically programming for an NVIDIA GPU, you will always want your vectors large enough to fully utilize **warps**
- A warp, simply put, is an optimized group of 32 threads
- To utilize warps in OpenACC, always make sure that your vector length is a **multiple of 32**

# CUDA PROGRAMMING MODEL REVIEW

- A grid is composed of blocks which are completely independent
- A block is composed of threads which can communicate within their own block
- 32 threads form a warp
- Instructions are issued per warp
- If an operand is not ready the warp will stall
- Context switch between warps when stalled



# GANG WORKER VECTOR

- Gang is a general term that can mean a few different things. In short, it depends on your architecture.
  - On a multicore CPU, generally gang=thread.
  - On a GPU, generally gang=thread block.
- The way I like to think of it is that gang represents my outer-most level of parallelism for any architecture I am running on.

# LOOP OPTIMIZATION RULES OF THUMB

- It is rarely a good idea to set the number of gangs in your code, let the compiler decide.
- Most of the time you can effectively tune a loop nest by adjusting only the vector length.
- It is rare to use a worker loop. When the vector length is very short, a worker loop can increase the parallelism in your gang.
- When possible, the vector loop should step through your arrays
- Use the `device_type` clause to ensure that tuning for one architecture doesn't negatively affect other architectures.

# MODULE REVIEW

# KEY CONCEPTS

In this module we discussed...

- The loop directive enables the programmer to give more information to the compiler about specific loops
- This information may be used for correctness or to improve performance.
- The device\_type clause allows the programmer to optimize for one device type without hurting others.



# LAB ASSIGNMENT

In this module's lab you will...

- Update the code from the previous module in attempt to improve the performance
- Use PGProf to analyze the performance difference when changing your loops
- Experiment with the `device_type` clause to ensure GPU optimizations don't slow down the multicore speed-up, or vice versa